



# Giving Linux a Camera Stack: libcamera's 3 Years Journey and Exciting Future

Embedded Linux Conference 2021  
Seattle, 2021-09-28

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# Once Upon A Time





Panasonic MC20 + Pinnacle Miro DC10

**In the beginning...**

**IDEAS  
ON BOARD**



Logitech Quickcam Express

**... were simple devices**



*A monolithic API for  
TV grabbers and  
webcams alike.*

A  
P  
I   /   +-----+  
         |   |   capture   |  
         |   |   /dev/video0   |  
         \   +-----+

*High-level controls,  
the TV signal  
provides a good  
image already.*

*Enables development of  
universal applications.*



**V4L2**



Logitech Quickcam Express For Notebooks

## Early UVC Camera

IDEAS  
ON BOARD

From: Laurent Pinchart <laurent.pinchart@skynet.be>  
To: linux-usb@vger.kernel.org, video4linux-list@redhat.com  
Subject: [PATCH] USB Video Class driver  
Date: Wed, 23 Apr 2008 01:37:11 +0200

Hi everybody,

after more than two years of development the Linux UVC driver is mostly ready to jump the fence and get included in the mainline kernel.

This driver aims to support video input devices compliant with the USB Video Class specification. This means lots of currently manufactured webcams, and probably most of the future ones.

I plan to submit the driver through the V4L subsystem, but I'd like it to get a proper review on both the linux-usb and video4linux mailing lists first.

Given the size of the patch I'm open to any suggestion that would make the review process easier.

Laurent Pinchart

(my humble 25 August 1991 moment)



# USB Video Class



Palm Treo 650 (PXA270, 0.3MP Camera)

# Embedded Cameras



From: Guennadi Liakhovetski <g.liakhovetski@pengutronix.de>  
To: video4linux-list@redhat.com  
Subject: [PATCH 1/6] soc\_camera V4L2 driver for directly-connected  
SoC-based cameras  
Date: Tue, 5 Feb 2008 18:46:13 +0100 (CET)

This driver provides an interface between platform-specific camera busses and camera devices. It should be used if the camera is connected not over a "proper" bus like PCI or USB, but over a special bus, like, for example, the Quick Capture interface on PXA270 SoCs. Later it should also be used for i.MX31 SoCs from Freescale. It can handle multiple cameras and / or multiple busses, which can be used, e.g., in stereo-vision applications.

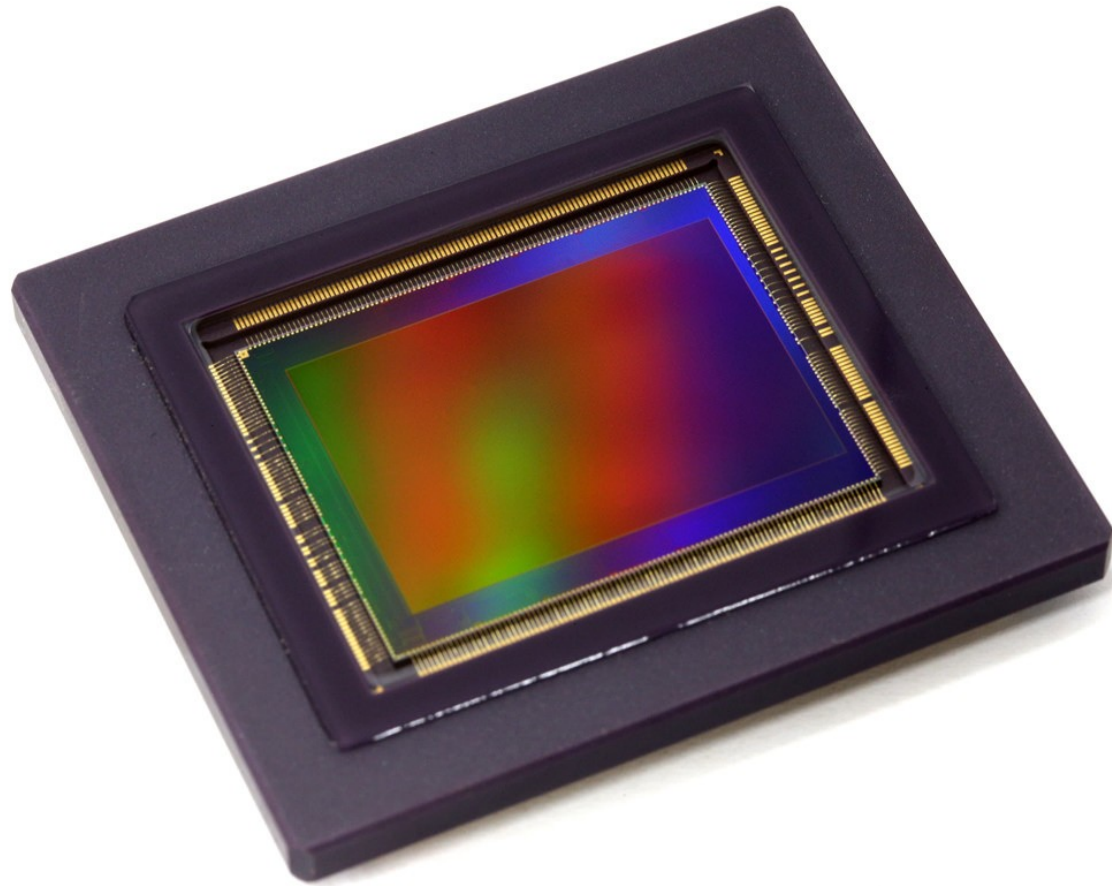
Signed-off-by: Guennadi Liakhovetski <g.liakhovetski@pengutronix.de>



## V4L2 Goes Embedded

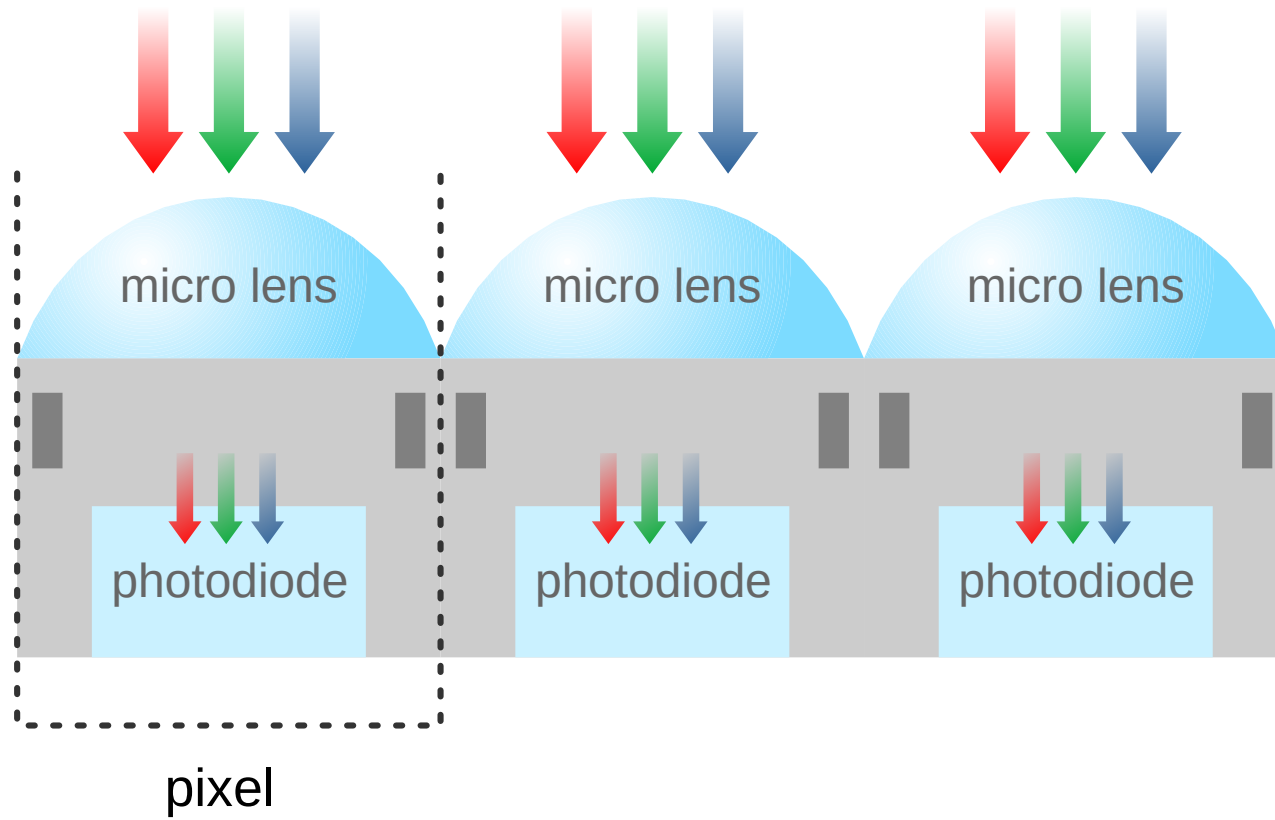
# What is a camera?



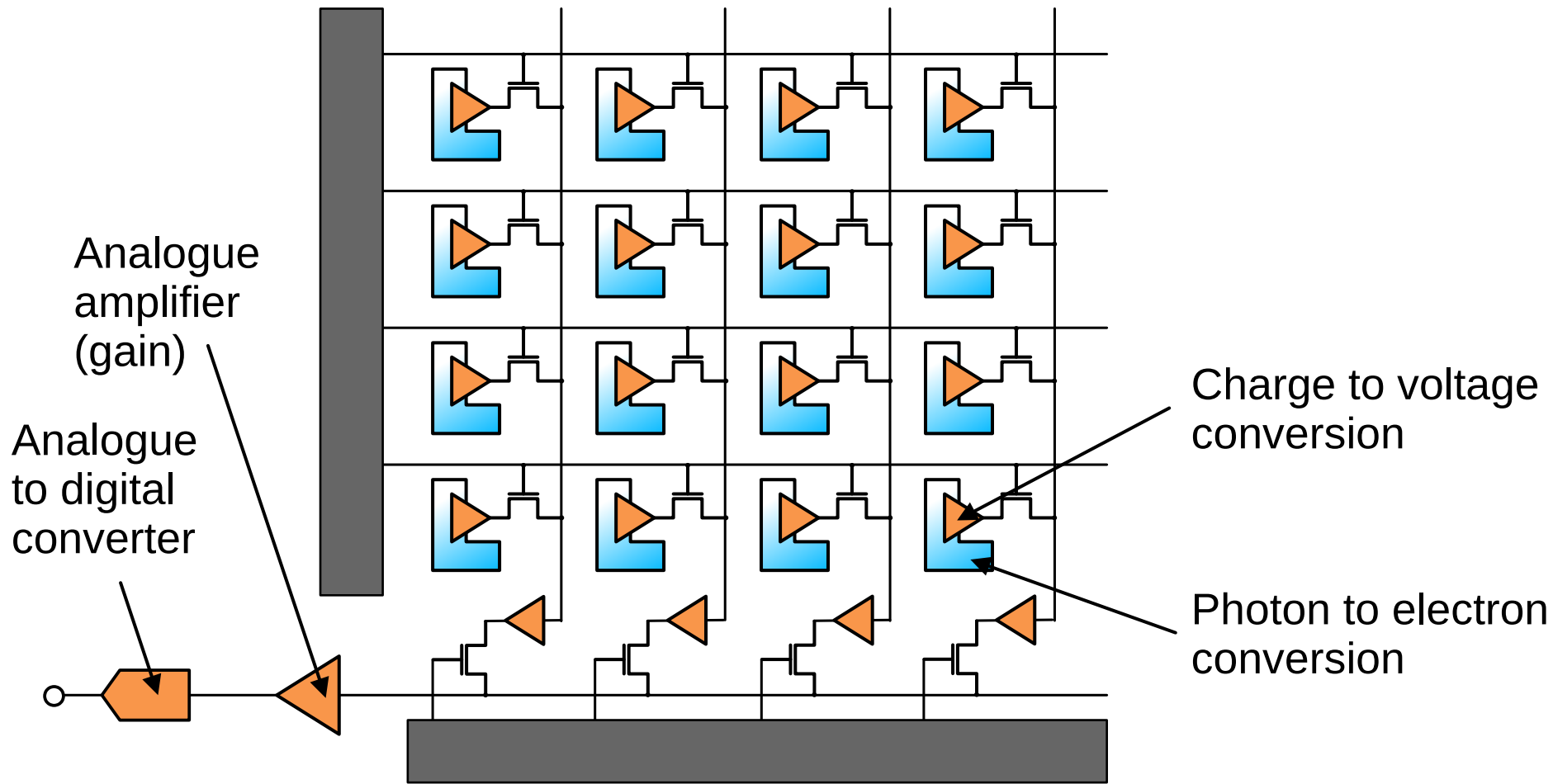


**CMOS Sensor**

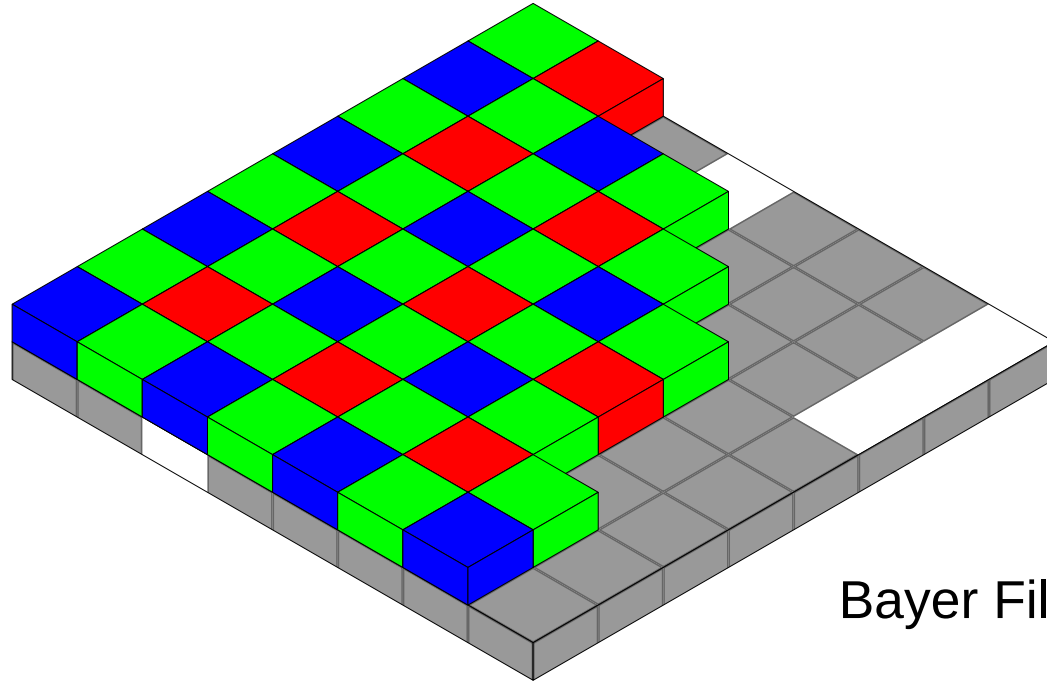




# CMOS Sensor



# CMOS Sensor



Bayer Filter



# Colour Filter Array

source: [https://en.wikipedia.org/wiki/Bayer\\_filter](https://en.wikipedia.org/wiki/Bayer_filter)



Original



120x80 Bayer image



# CFA Interpolation

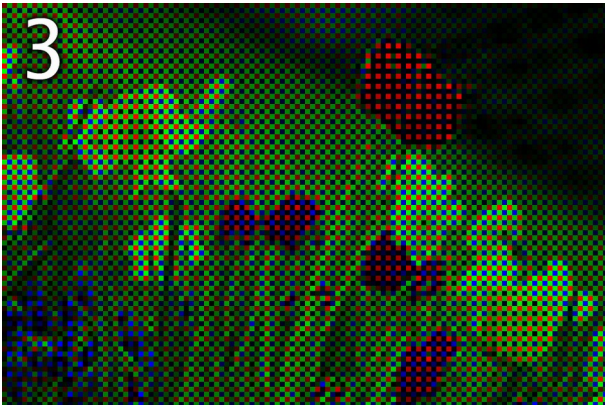
source: [https://en.wikipedia.org/wiki/Bayer\\_filter](https://en.wikipedia.org/wiki/Bayer_filter)



Original



120x80 Bayer image



Colour-coded

# CFA Interpolation

source: [https://en.wikipedia.org/wiki/Bayer\\_filter](https://en.wikipedia.org/wiki/Bayer_filter)



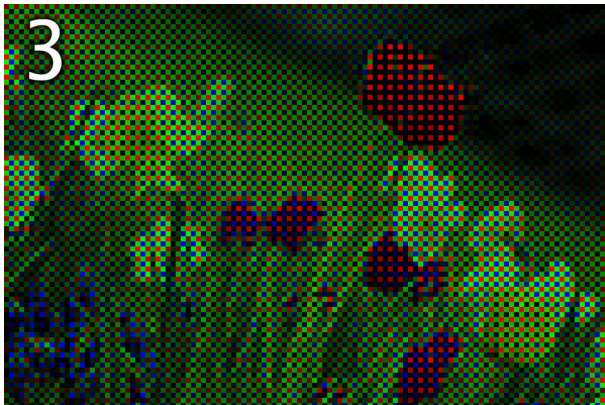




Original



120x80 Bayer image



Colour-coded



Colour interpolation

# CFA Interpolation

source: [https://en.wikipedia.org/wiki/Bayer\\_filter](https://en.wikipedia.org/wiki/Bayer_filter)

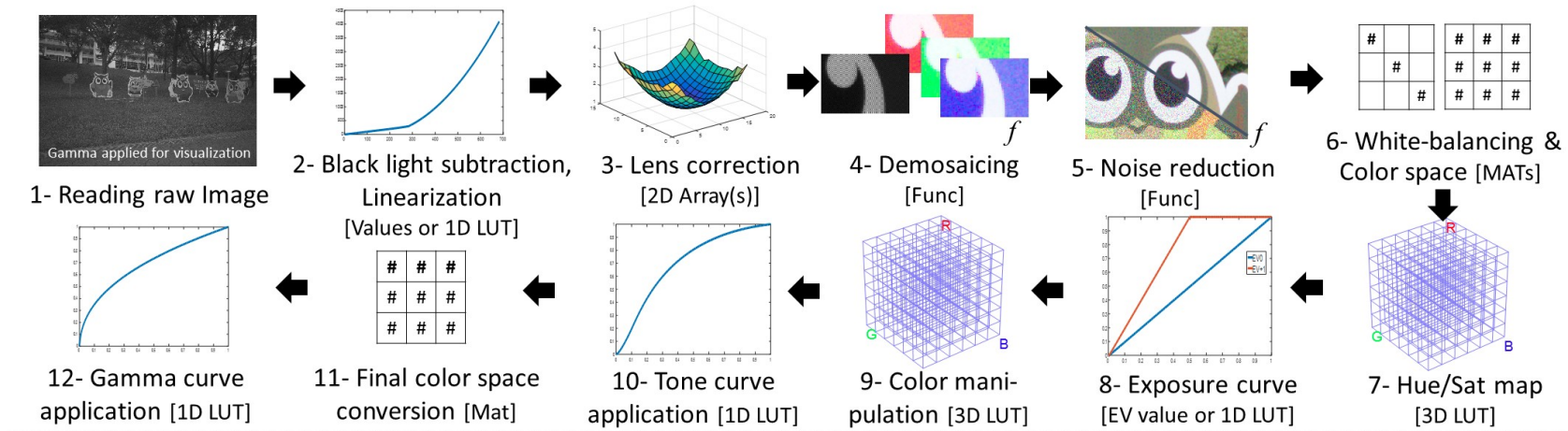




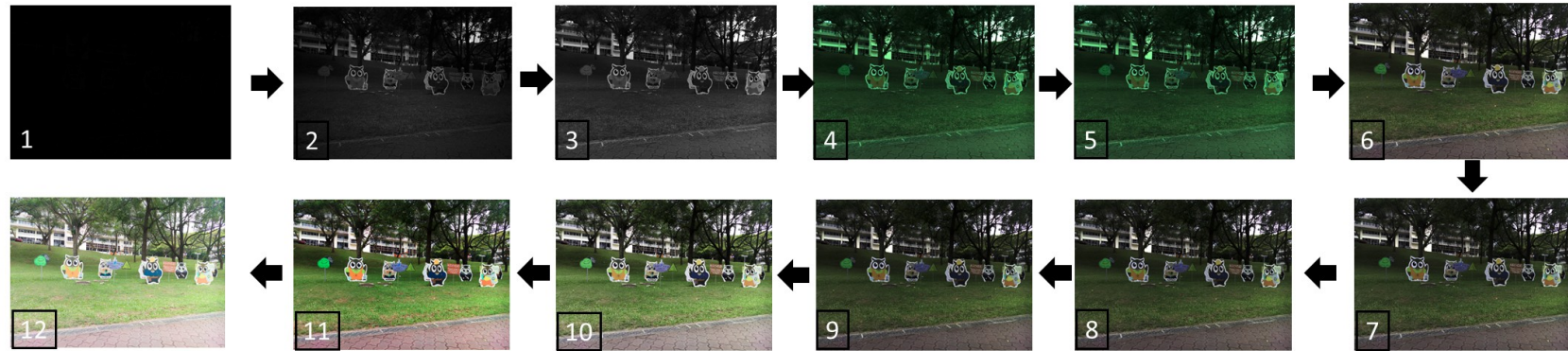
# Lens Shading



## Stages of the camera imaging pipeline and associated parameters

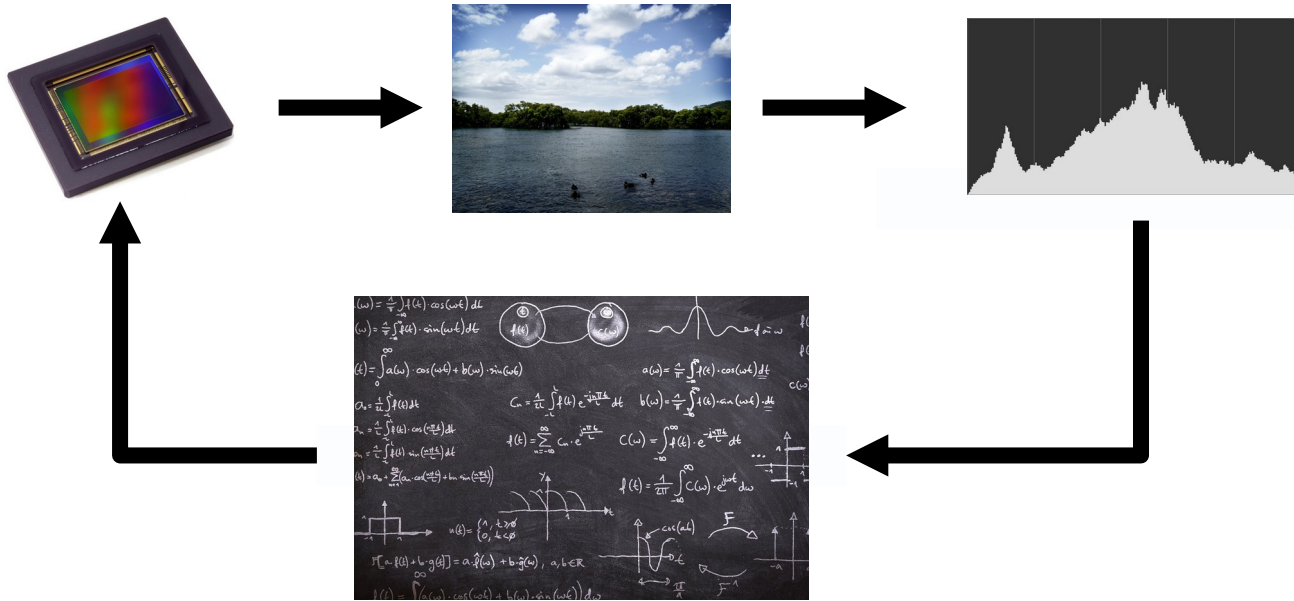


## Intermediate images for each stage



# Camera Pipeline

source: <https://karaimer.github.io/camera-pipeline/>



# Auto Algorithms (a.k.a. 3A)

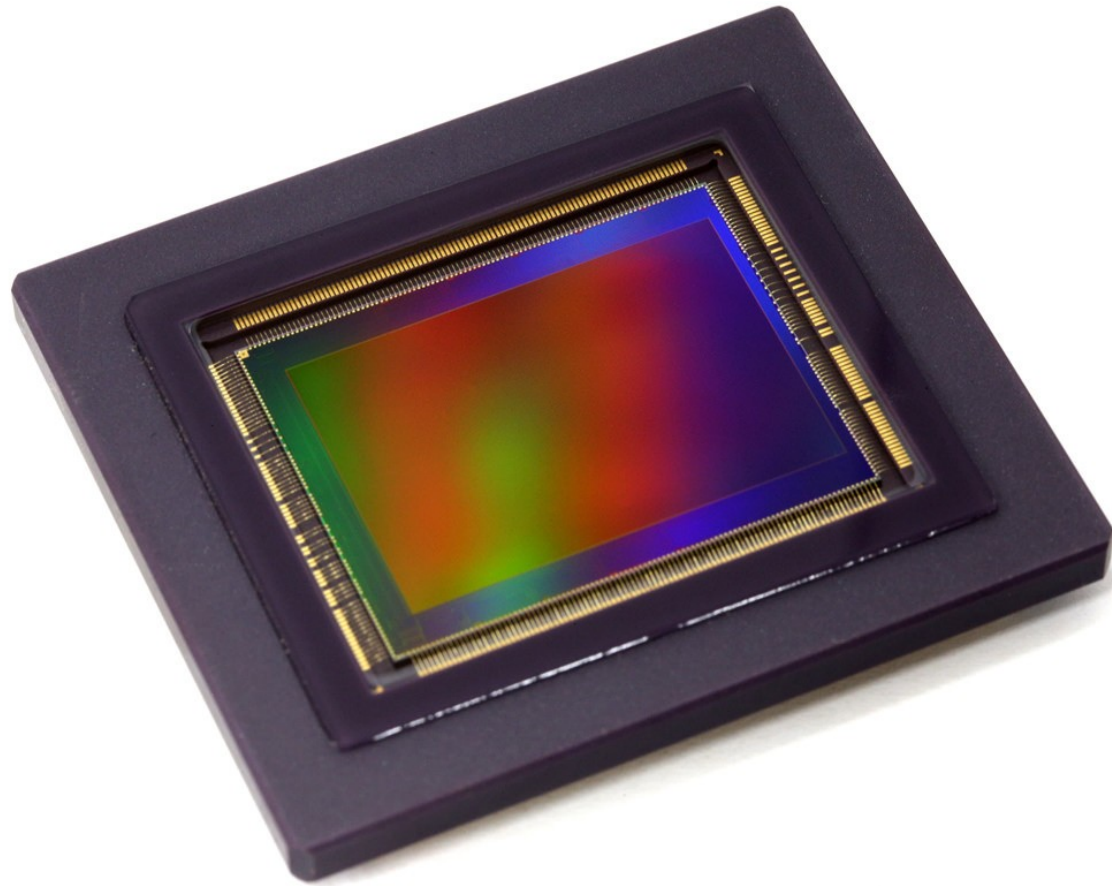


# IQ Tuning

source: <https://www.flickr.com/photos/davedugdale/15043975135>

# Back To V4L2





**Smart Sensor (a.k.a. YUV Sensor)**



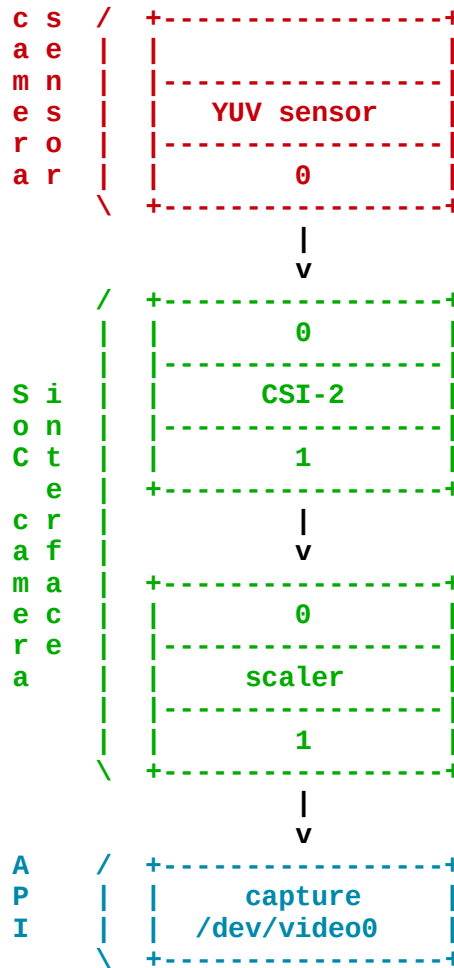


Logitech Quickcam Express For Notebooks

**So Small, Yet So Smart**

**IDEAS  
ON BOARD**

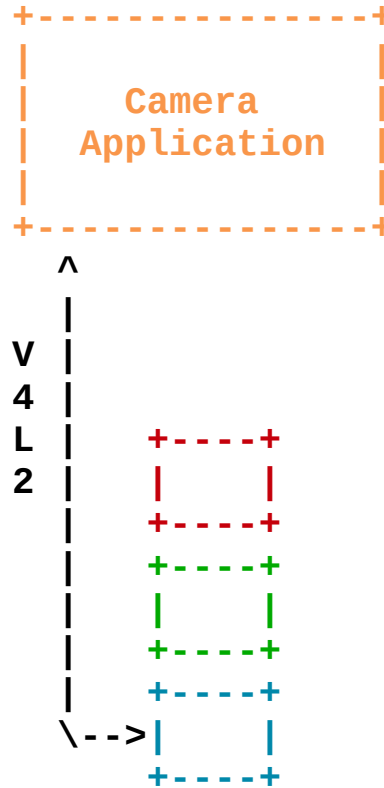




*In the beginning were  
simple pipelines...*

# V4L2 Goes Embedded

*... and they were  
simple to control,  
with a single API.*



## V4L2 Goes Embedded

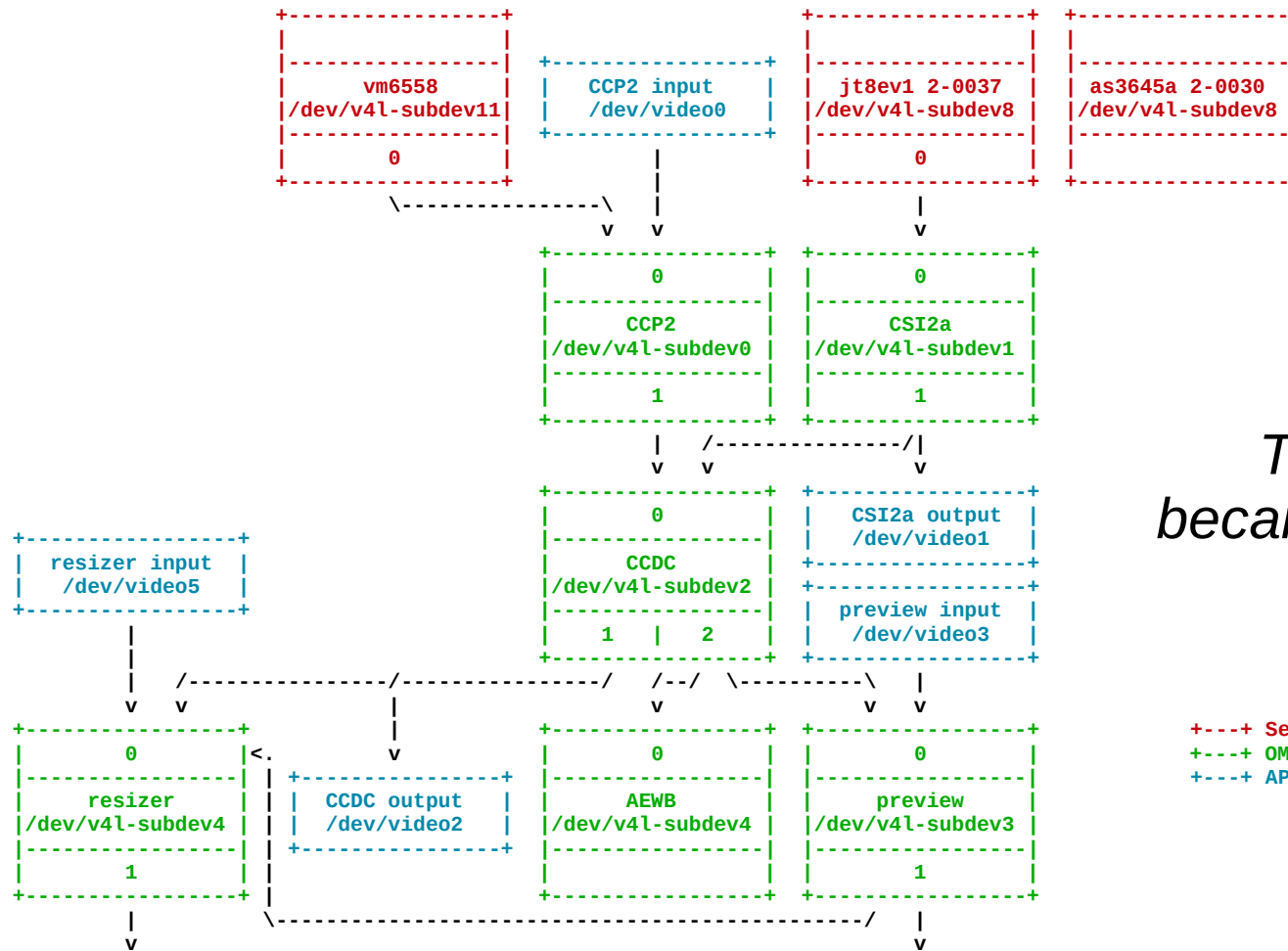




**Then the world became complex**

+ - / \ - +  
| (o) |  
+ - - - - +

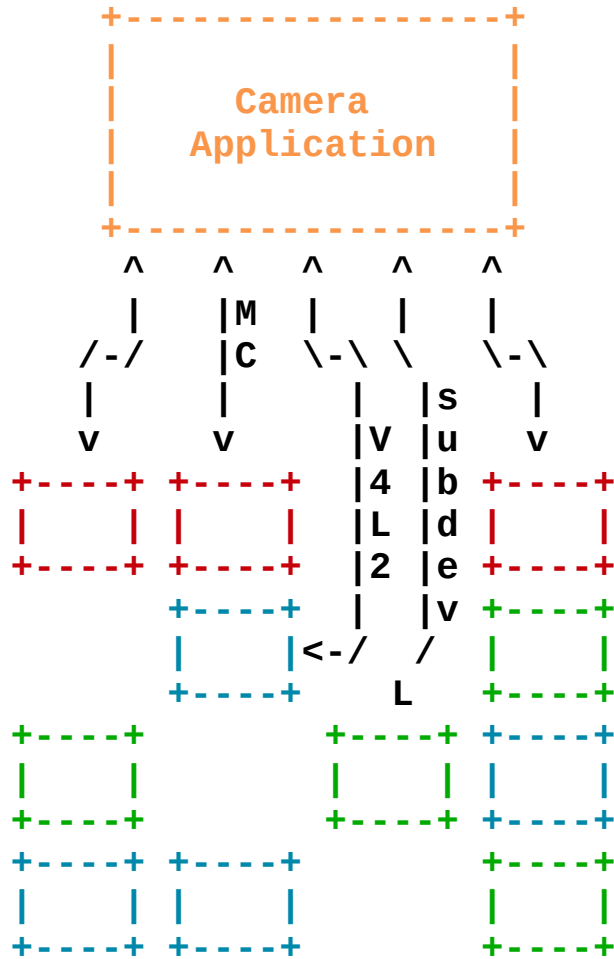
# The libcamera Journey



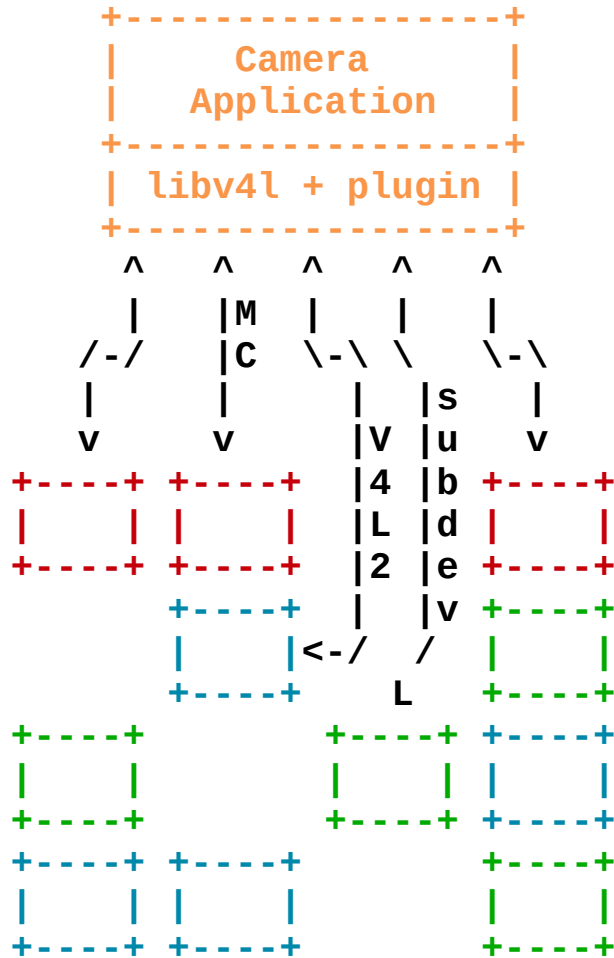
*Then the world became complex...*

# OMAP3 Camera in Nokia N900

*... and application developers were left suffering.*



*Solutions were  
proposed...*





*... but never  
implemented.*



*The world turned  
dark...*





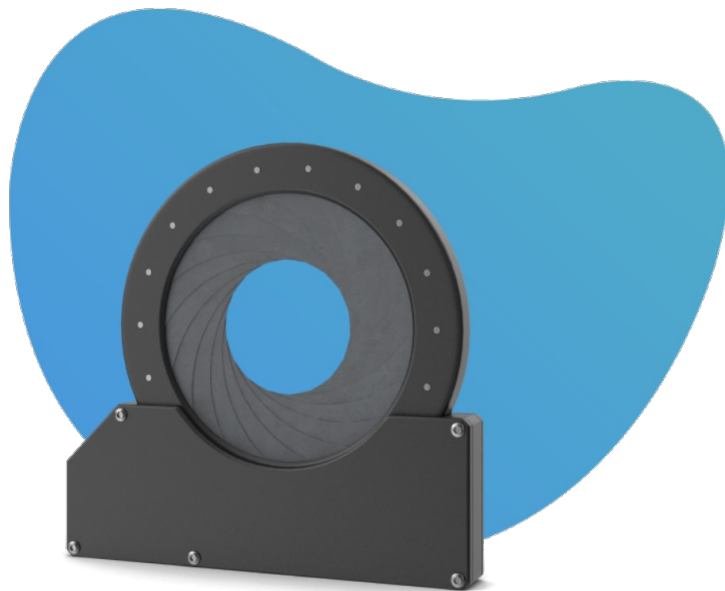
# Acer Chromebook Tab 10

IDEAS  
ON BOARD



# Dell Latitude 7285

*...then hope came  
back.*



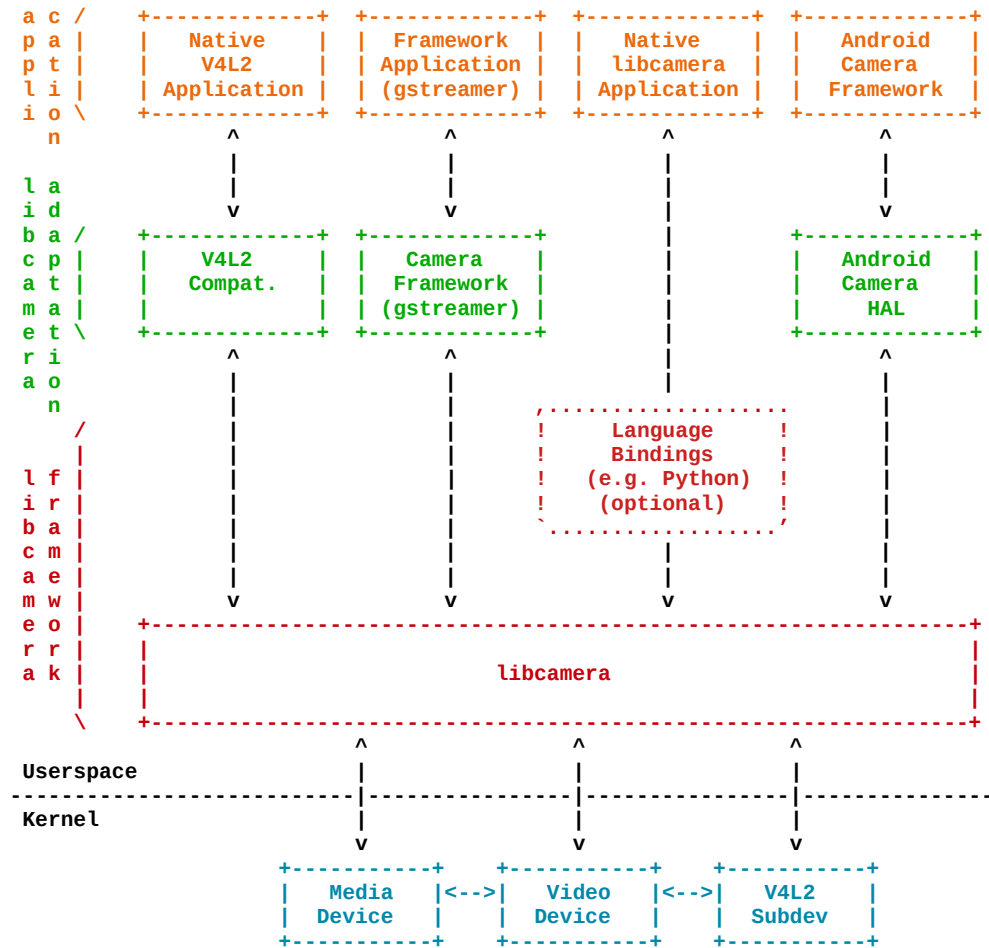
# Hi, we're libcamera.

An open source camera stack and framework for Linux, Android, and ChromeOS

[Getting Started](#)

**IDEAS**  
ON BOARD

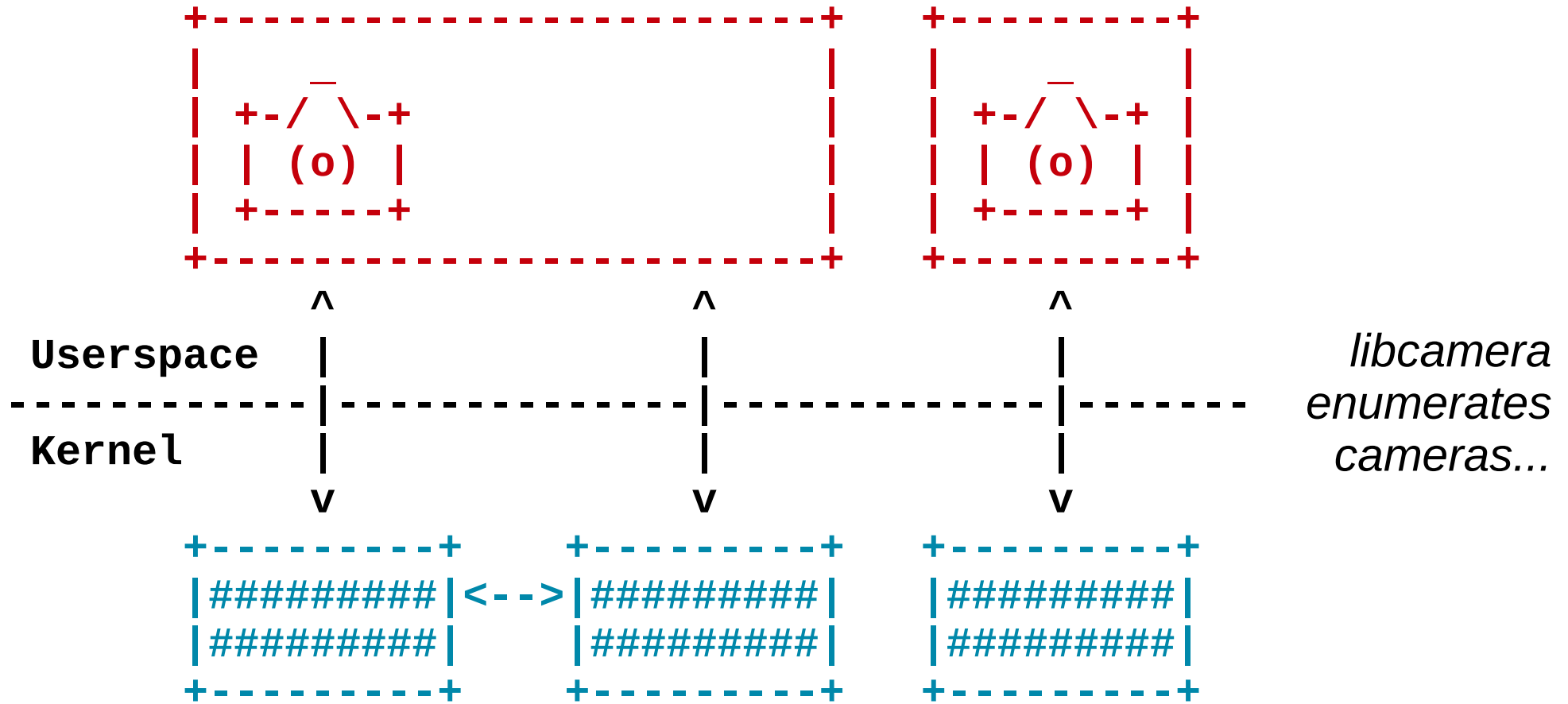
*libcamera provides a complete userspace camera stack.*



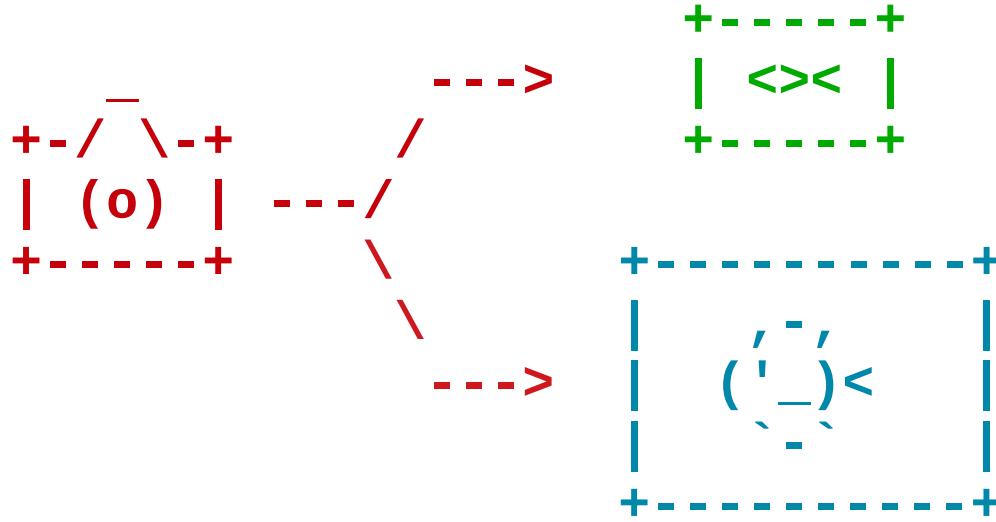
*The 'Mesa' of the camera world.*

# Camera Stack



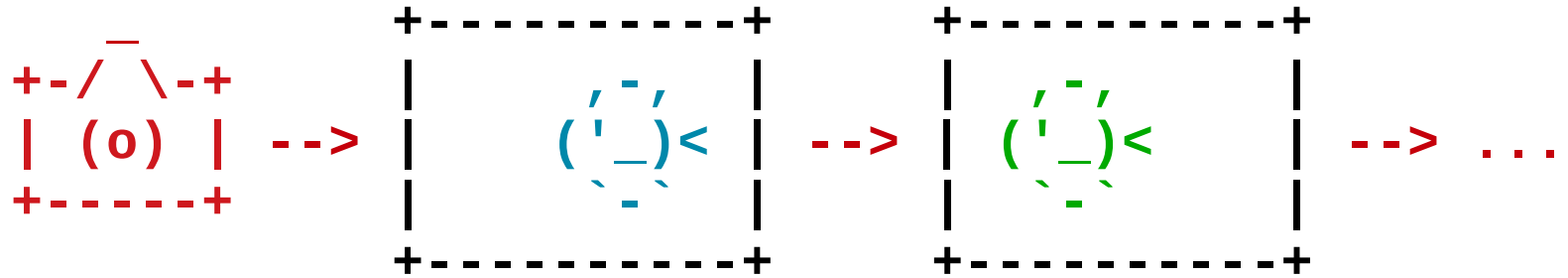


# Camera Devices & Enumeration



*It supports multiple  
concurrent streams  
for the same  
camera...*

# Streams

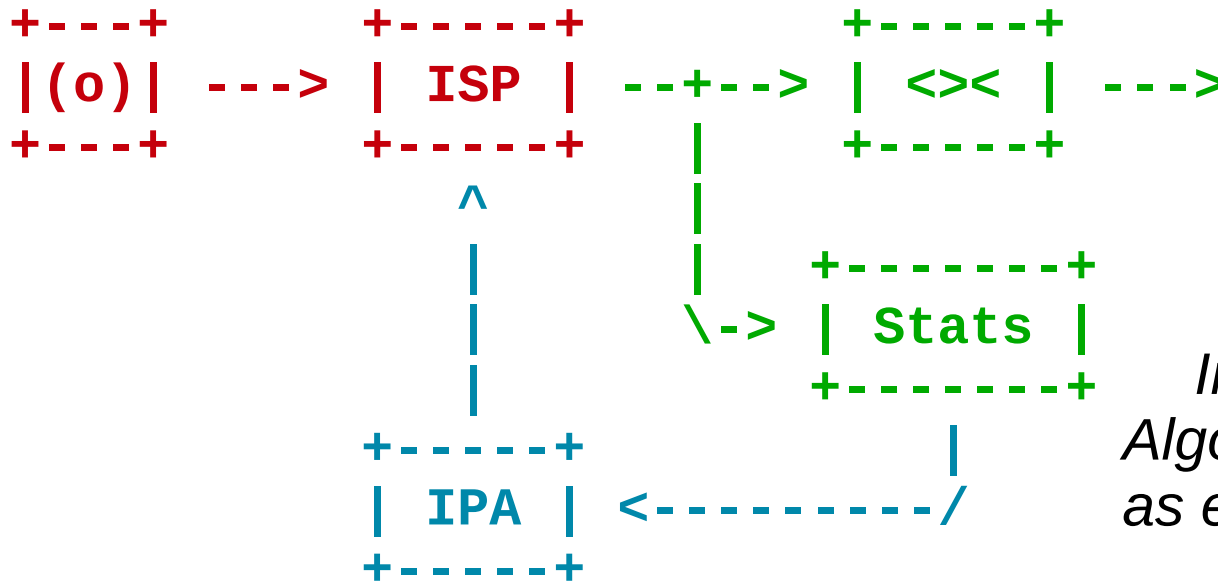


*... and per-frame controls.*

## Per-Frame Controls







*Image Processing  
Algorithm are loaded  
as external modules.*



# Image Processing Algorithms (3A)

+ - - - - +  
| V4L2 App. |  
+ - - - - +

+ - - - - +  
| V4L2  
API |  
+ - - - - +

+ - - - - +  
| libcamera |  
+ - - - - +

*Adaptation layers  
offer backward  
compatibility with  
existing APIs...*

# Adaptation



+-----+  
| V4L2 App. |  
+-----+

+-----+  
| Android |  
+-----+

+-----+  
| V4L2  
API |  
+-----+

+-----+  
| \\_\_\_\_/ |  
/ . . \
!
!
-----
+-----+

*... and integrate  
libcamera with  
other operating  
systems.*

+-----+  
| libcamera |  
+-----+



# Adaptation

+ - / \ - +  
| (o) |  
+ - - - - +

# The libcamera Journey



Intel IPU3 (Kaby Lake)  
on HP Chromebook x2



USB Video Class (UVC)

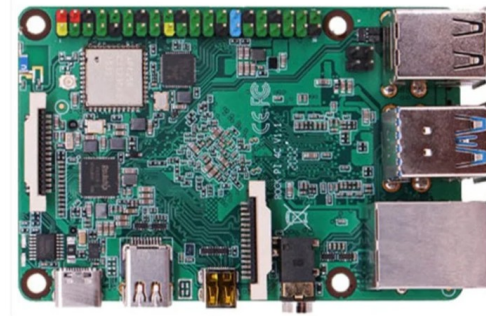
# Our Initial Targets



# Test, Test, Test



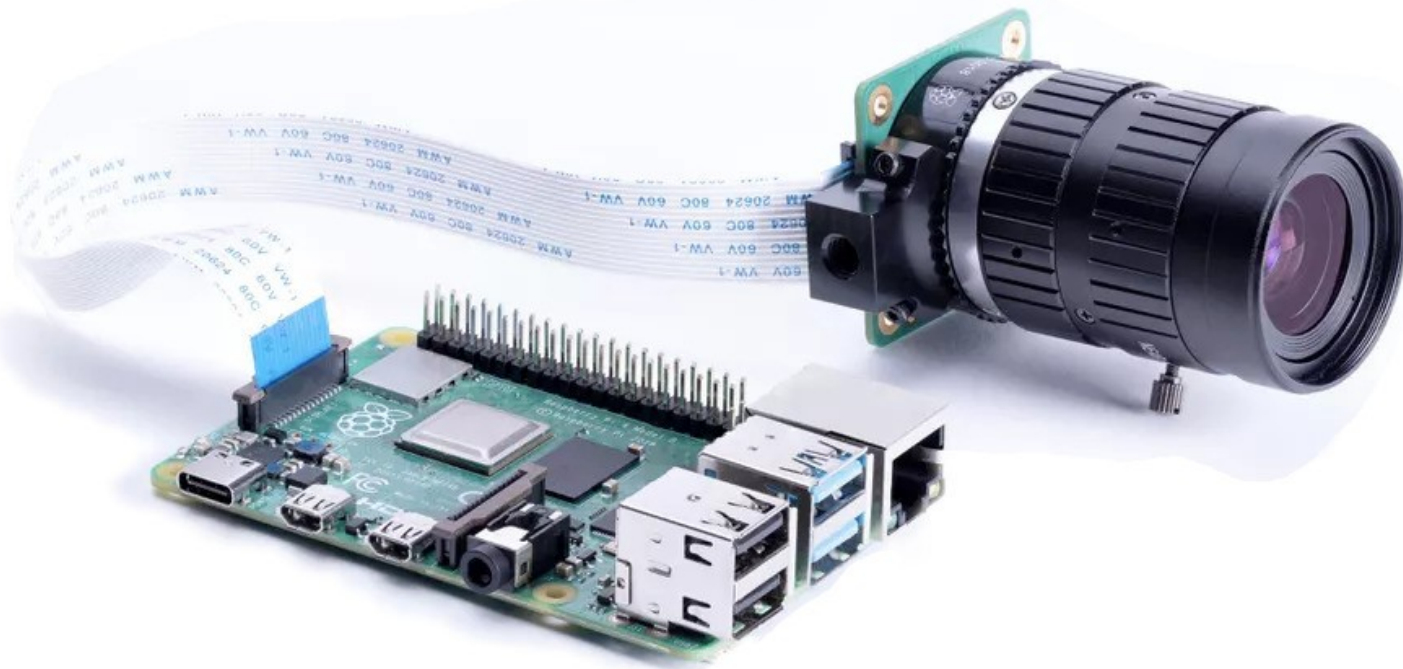
Acer Chromebook Tab 10



ROCK PI 4



**And ARM Too (RK3399)**



# Raspberry Pi 4 + IMX477





## Raspberry Pi Blog

[← All blog posts](#)[📅 ARCHIVE](#) [📡 RSS](#)

# An open source camera stack for Raspberry Pi using libcamera



4th May 2020 David Plowman 39 comments

Since we released the first Raspberry Pi camera module back in 2013, users have been clamouring for better access to the internals of the camera system, and even to be able to attach camera sensors of their own to the Raspberry Pi board. Today we're releasing our first version of a new open source camera stack which makes these wishes a reality.

(Note: in what follows, you may wish to refer to the [glossary](#) at the end of this post.)

We've had the building blocks for connecting other sensors and providing lower-level access to the image processing for a while, but Linux has been missing a convenient way for applications to take advantage of this. In late 2018 a group of Linux developers started a project called [libcamera](#) to address that. We've been working with them since then, and we're pleased now to announce a camera stack that operates within this new framework.

### RELATED POSTS



**New product: Raspberry Pi High Quality Camera on sale now at \$50**



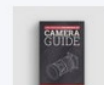
**Controlling Telescopes with Raspberry Pi and Mathematica**

### NEXT POST



**How to work from home with Raspberry Pi | The Magpi 93**

### PREVIOUS POST



**New book: The Official Raspberry Pi Camera Guide**

# An Unexpected Friend

IDEAS  
ON BOARD



**IDEAS ON BOARD**

# Microsoft Surface Go 2

Search or jump to... Pull requests Issues Marketplace Explore

linux-surface / linux-surface Sponsor Watch 88 Unstar 1.6k Fork 91

Code Issues 189 Pull requests Discussions Actions Projects Wiki Security Insights

## Camera support #91

New issue

Open jrevillard opened this issue on 19 Feb 2020 · 1,036 comments

jrevillard commented on 19 Feb 2020 • edited by archseer

I see that there is some activity here: [jakeday/linux-surface#145](#)

I think it's better to trace it here isn't it ?

Best,  
Jerome

Maintainer note: [There is a BountySource bounty available for this issue](#). If you'd like to see a camera driver consider donating to incentivise the work.

3

mmalmeida commented on 19 Feb 2020 • edited

I agree

qzed commented on 19 Feb 2020 Member

Right, makes sense to track this here.

qzed added C: missing feature D: Surface Book D: Surface Book 2 D: Surface Pro 4 D: Surface Pro 5 D: Surface Pro 6

Assignees  
No one assigned

Labels  
A: cameras C: missing feature  
D: Surface Book D: Surface Book 2  
D: Surface Go D: Surface Laptop  
D: Surface Laptop 2 D: Surface Pro 4  
D: Surface Pro 5 D: Surface Pro 6

Projects  
None yet

Milestone  
No milestone

Linked pull requests  
Successfully merging a pull request may close this issue.  
None yet

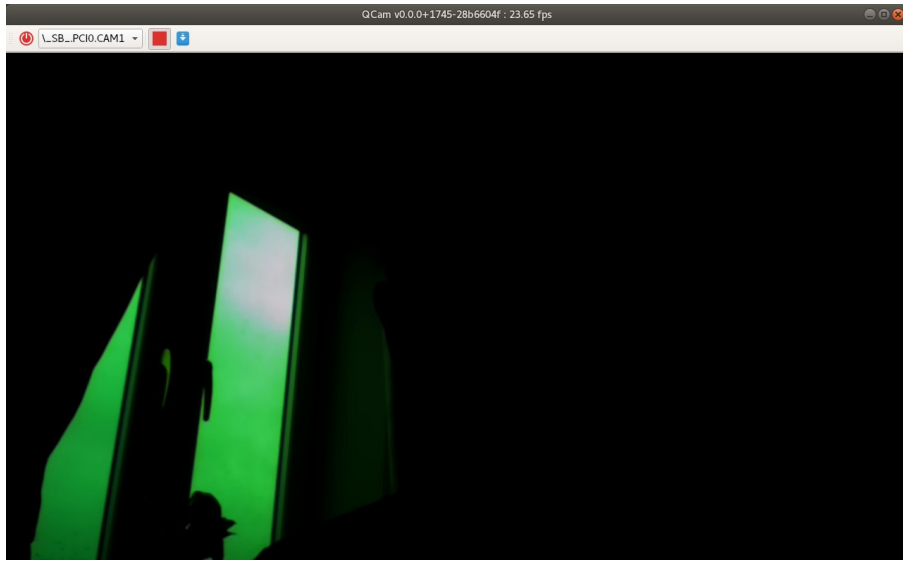
Notifications  
Unsubscribe  
You're receiving notifications because you were mentioned

*"I found libcamera based on this bug report, it seems to have the required userspace code to have ipu3 working on 5.0."*

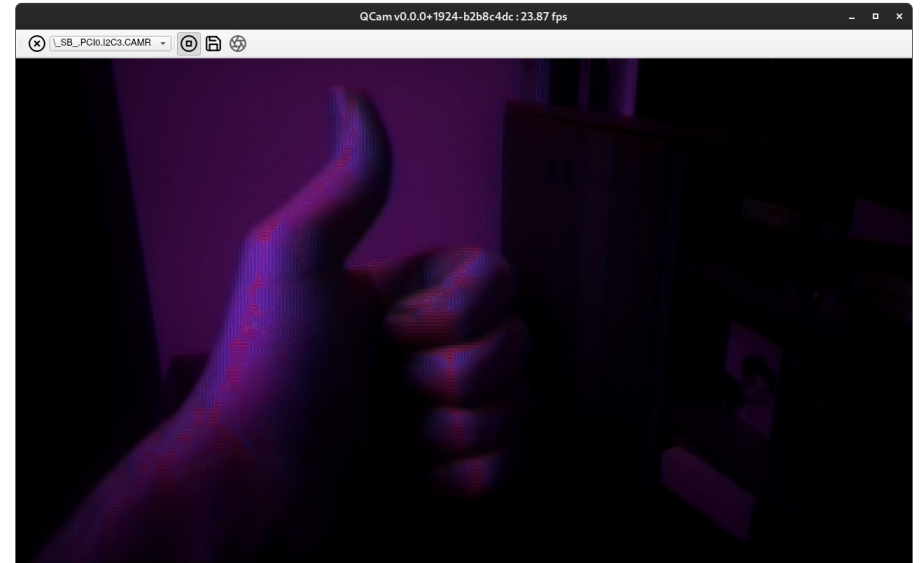
(archseer)



github.com/linux-surface



*Initial support status with work  
on kernel drivers from djrscally,  
kitakar5525 and qzed*



# linux-surface



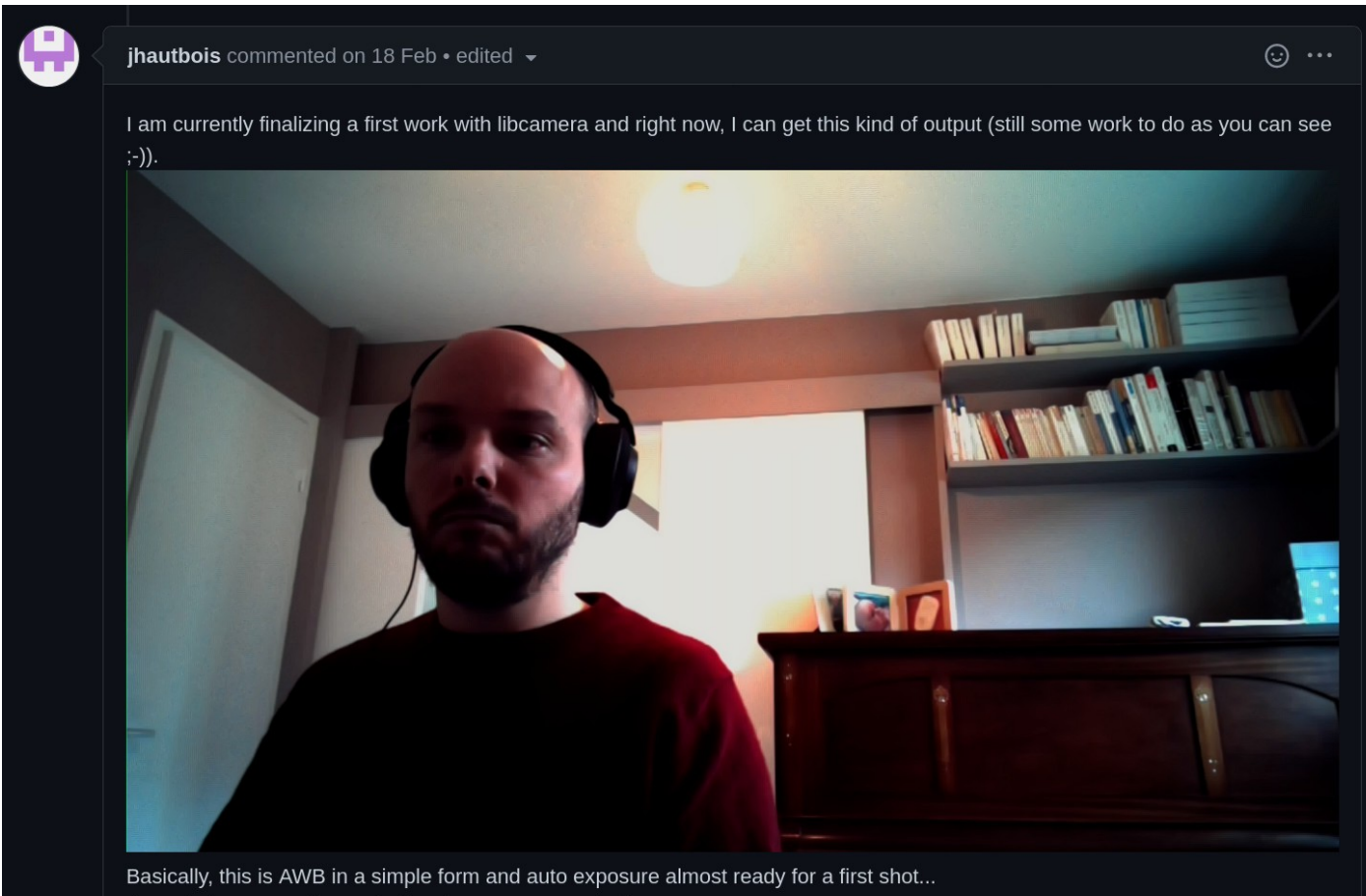
It seems that it tends to be purple-ish when it's dark and tends to be green-ish when it's bright.



*The sky after rain with leaf* taken by [surface-ipu3-cameras/ov8865\\_from\\_ov8856](#)



# Artwork



# libcamera Involvement

Open

## Camera support

linux-surface

19 February 2020 Posted by jrevillard

I see that there is some activity here: <https://github.com/jakeday/linux-surface/issues/145>

I think it's better to trace it here isn't it ?

Best,  
Jerome

Maintainer note: [There is a BountySource bounty available for this issue](#). If you'd like to see a camera driver consider donating to incentivise the work.

[Hide](#)
[View in GitHub](#)

SOLVE ISSUE

Overview

Backers (27)

Updates

TOTAL BOUNTY VALUE

\$810.00USD

\$15

\$50

\$500

- or -

15

USD

\*Minimum \$5 USD

Expires

Never

Select payment method

☐ PayPal

CHECKOUT

Are you a developer who can solve this issue?

Get Started

**IDEAS  
ON BOARD**

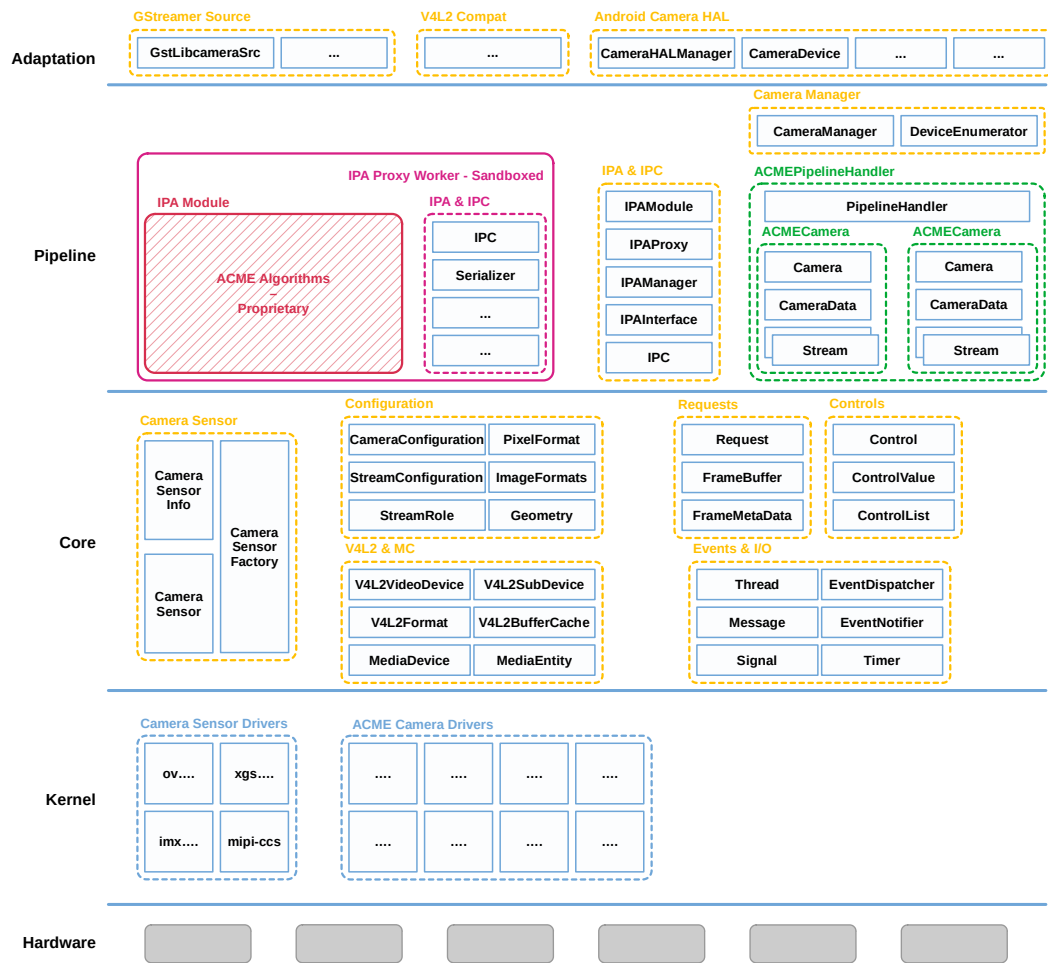
# Budget Expectations

+ - / \ - +  
| (o) |  
+ - - - - +

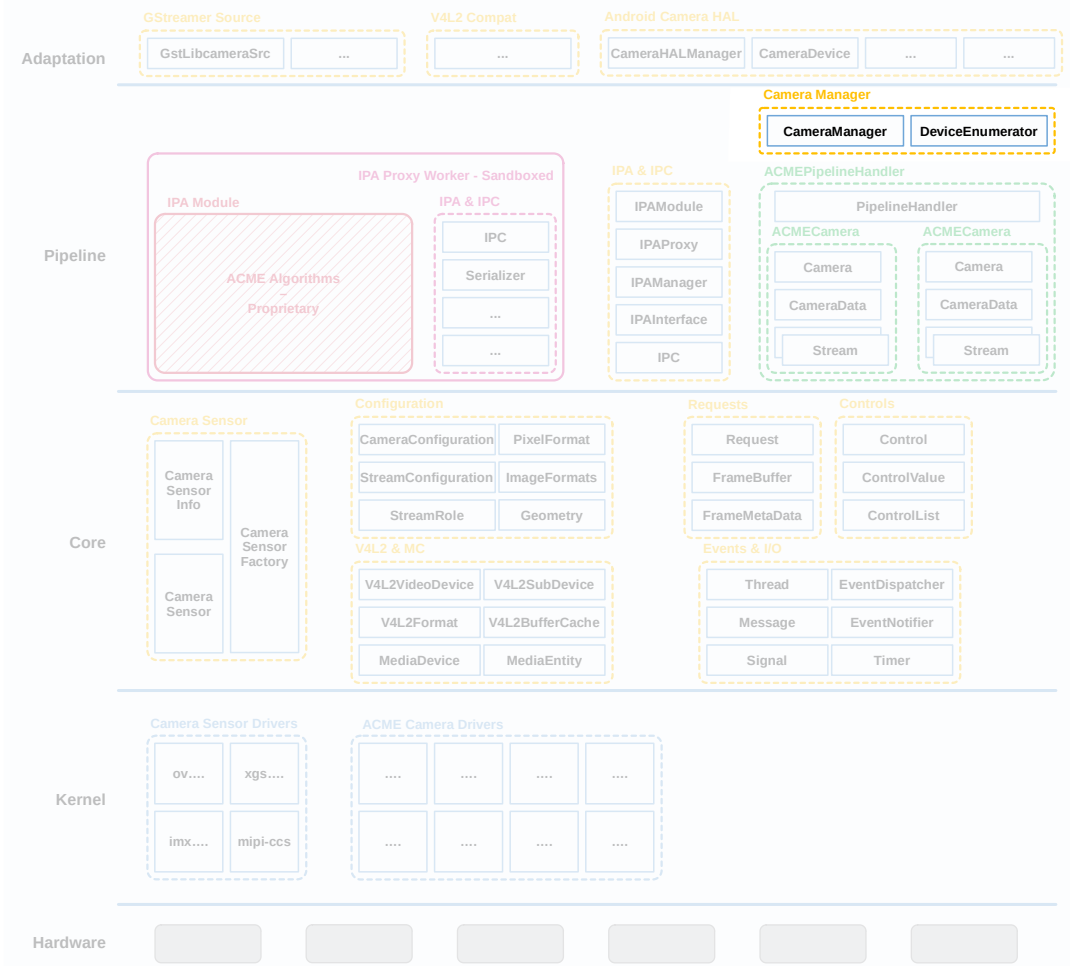
libcamera  
Today

IDEAS  
ON BOARD

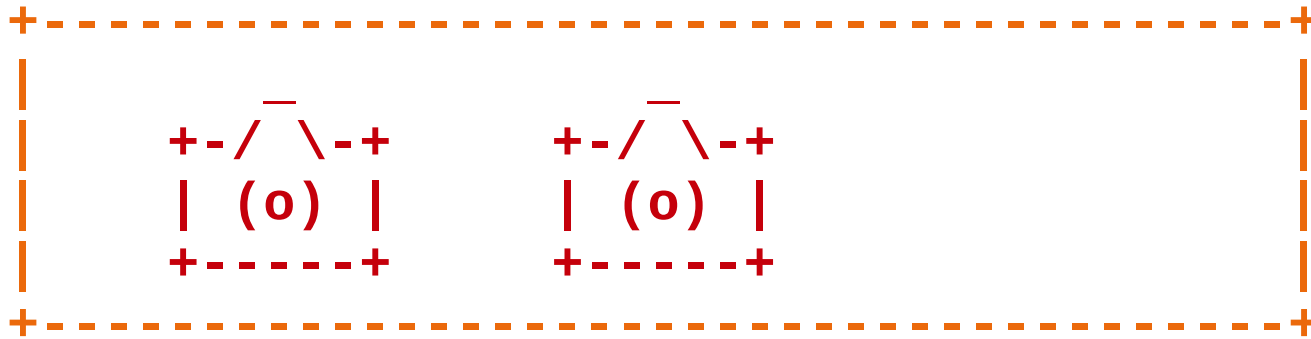




# The Camera Stack



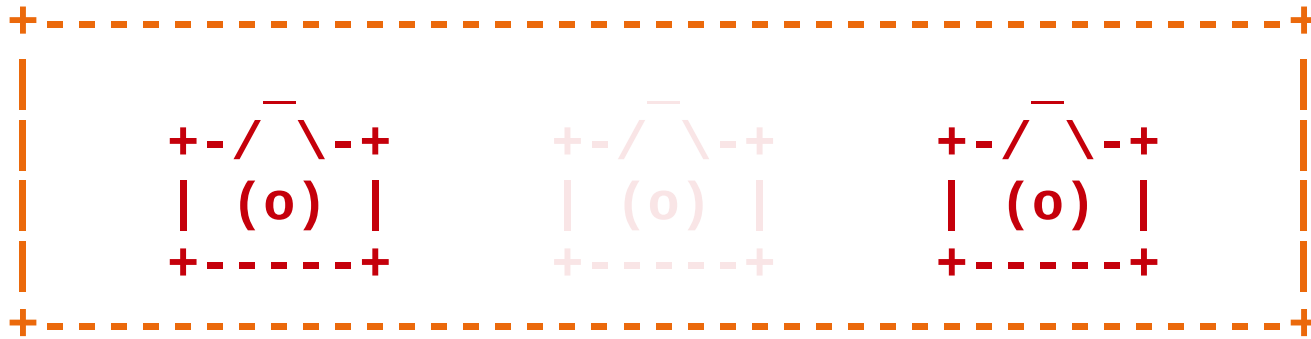
# The Camera Manager



*The Camera Manager  
enumerates media  
devices and instantiates  
corresponding pipeline  
handlers.*

# The Camera Manager

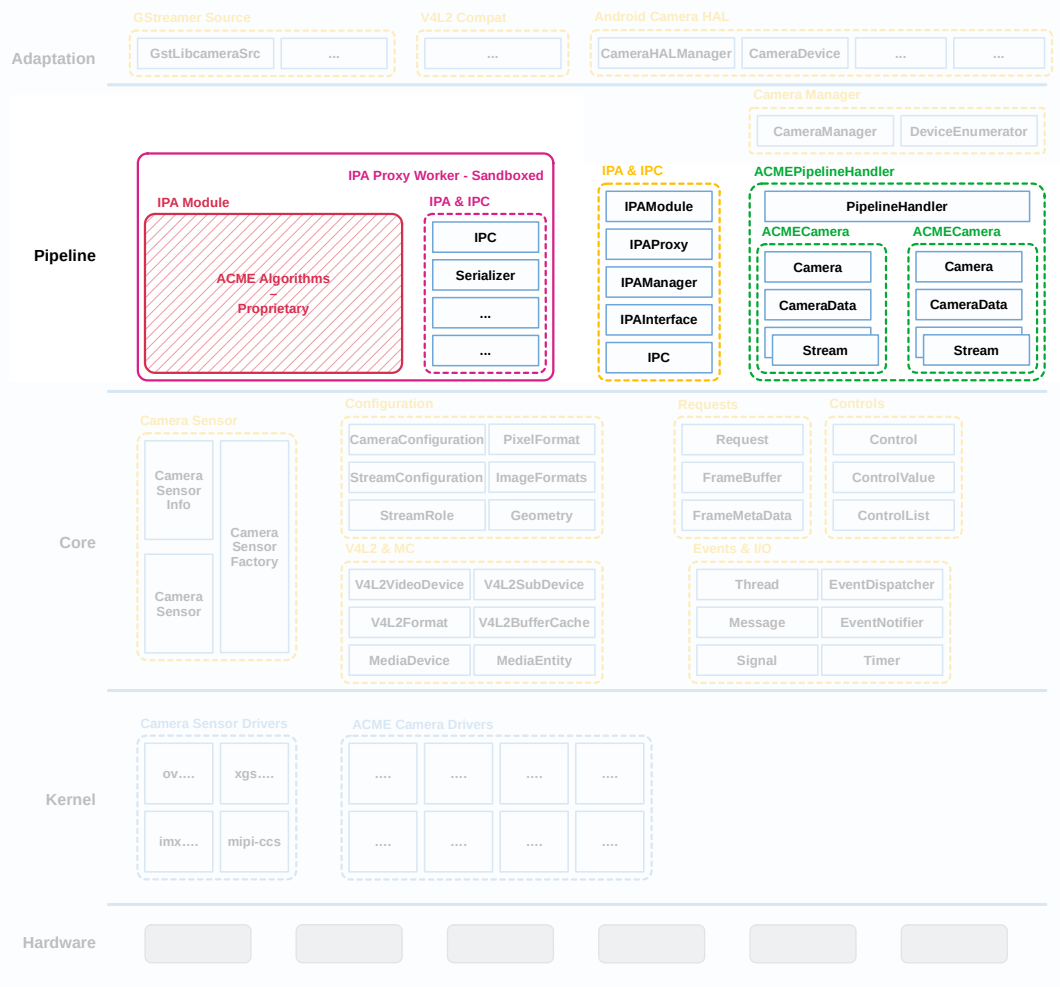




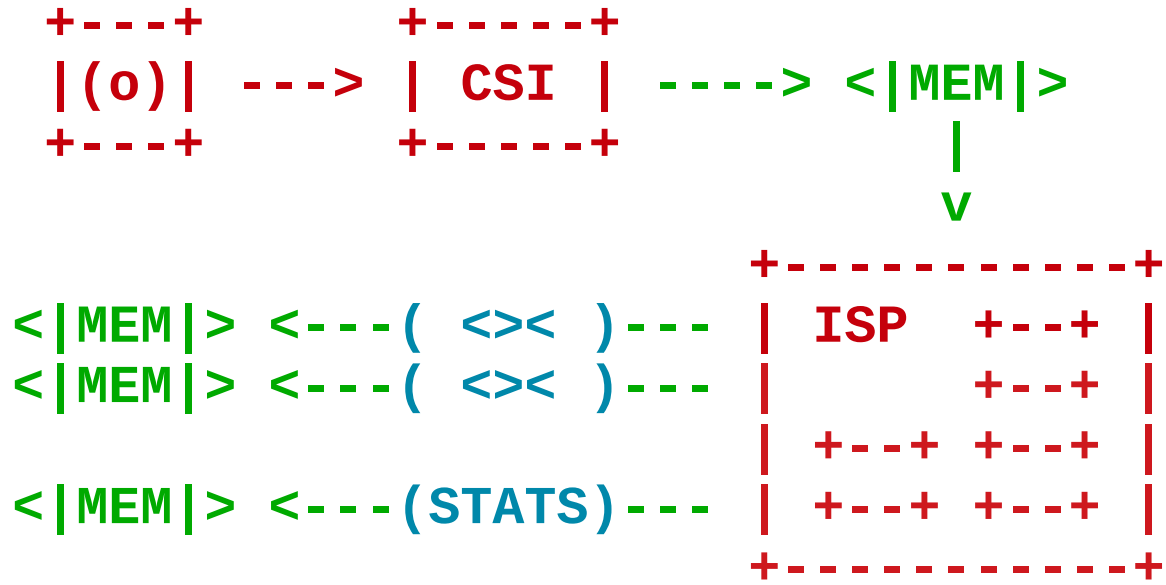
*Each pipeline handlers create and register one or more cameras.*



# The Camera Manager



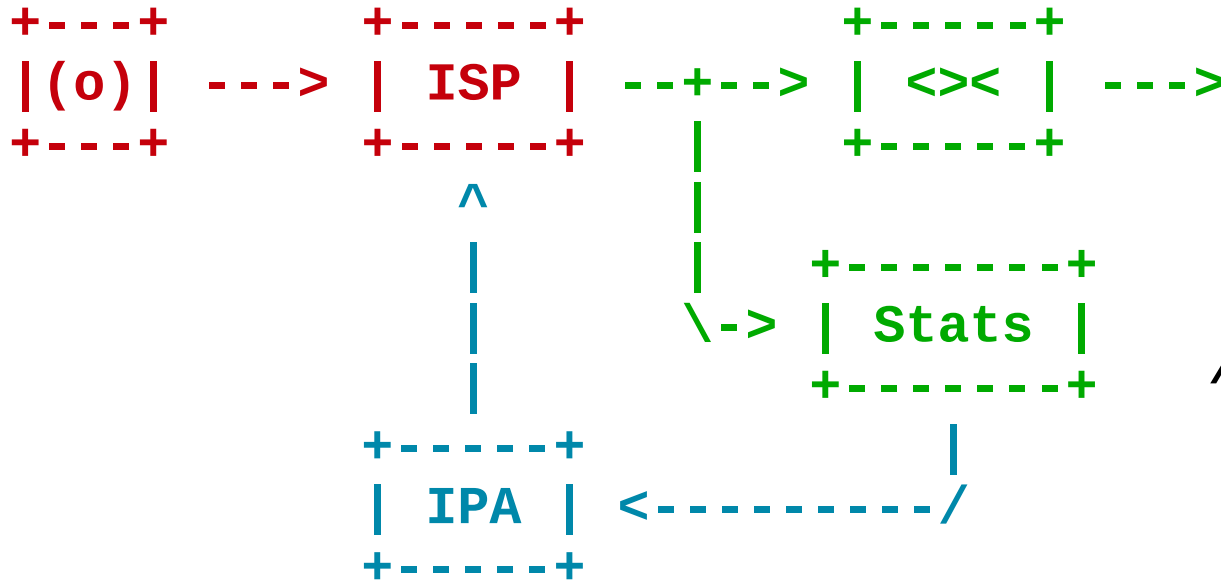
# The Pipeline



*The pipeline handler interfaces with all kernel devices. It abstracts them and exposes video streams to upper layers.*



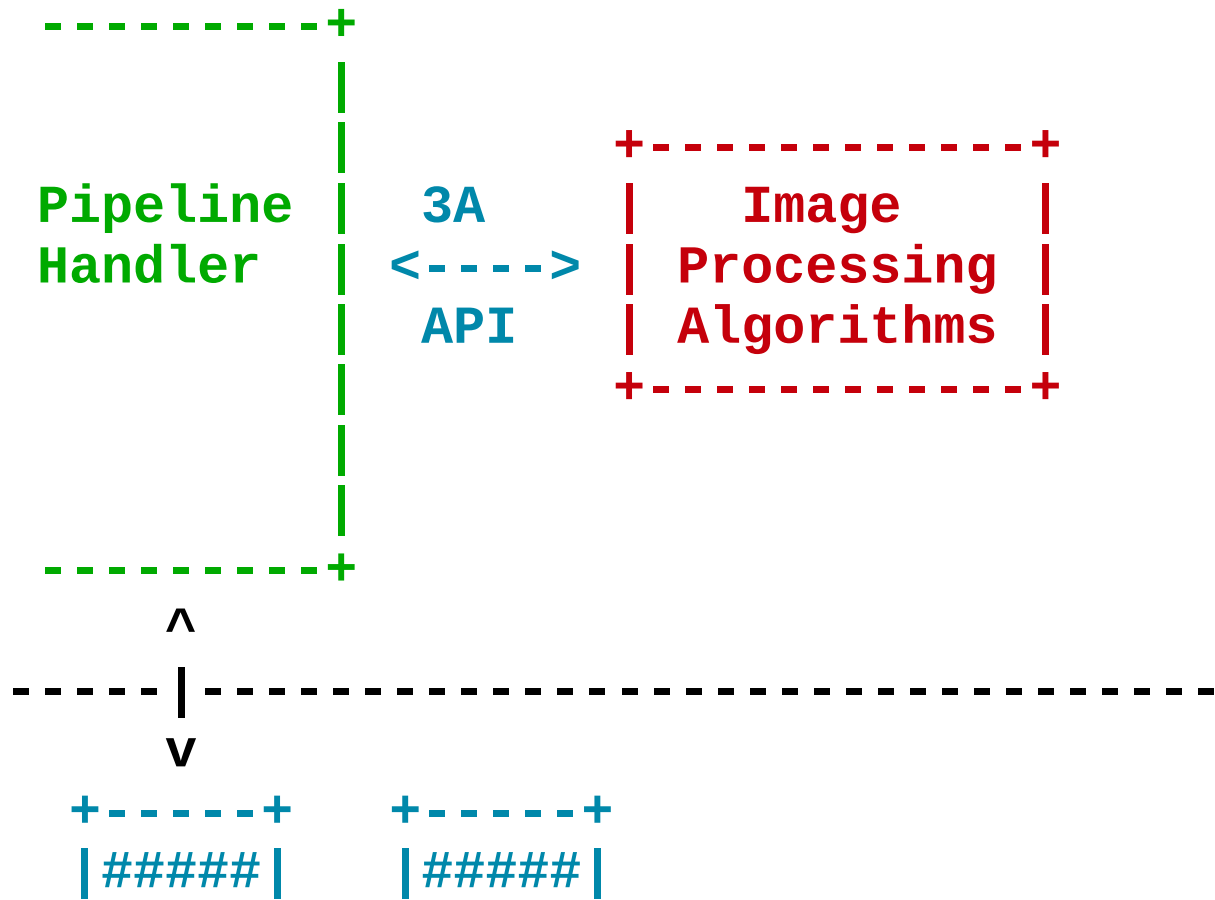
# The Pipeline Handler



*Image Processing Algorithms (IPA) receive statistics from the hardware and compute optimal image parameters.*

# The Image Processing Algorithms



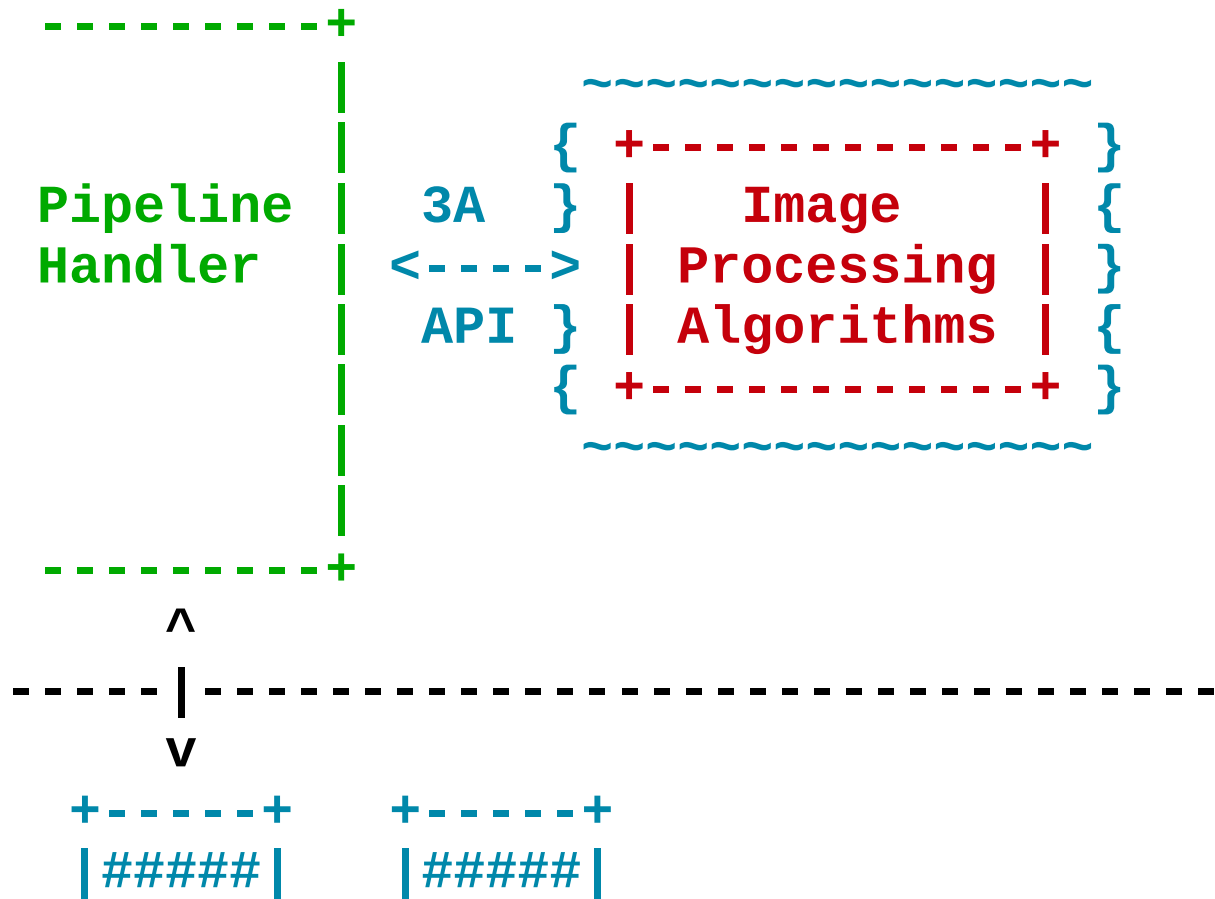


*IPAs are separate modules that don't access kernel devices directly. They only have access to their pipeline handler through the IPA API.*

# The Image Processing Algorithms



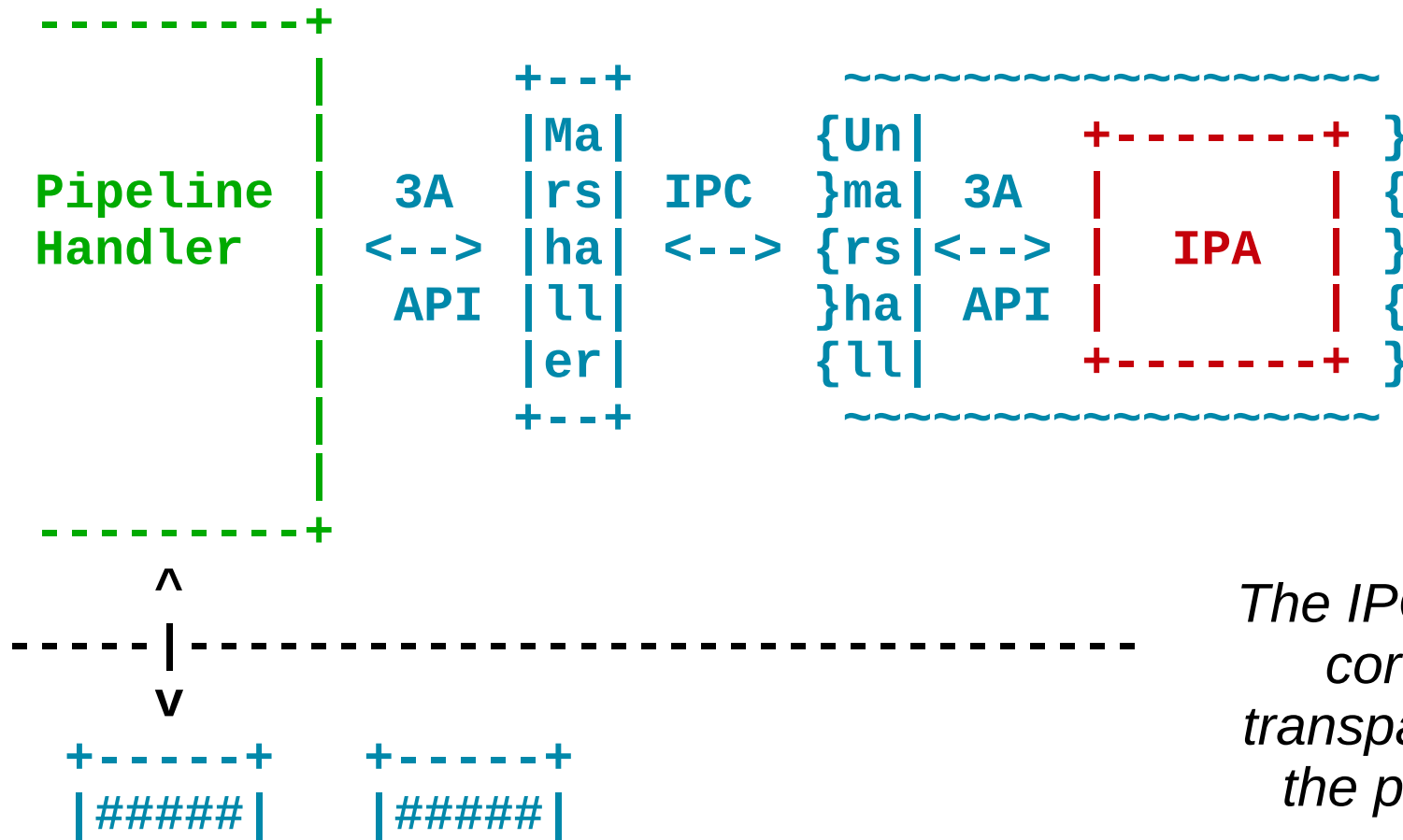




*Out-of-tree (including closed-source) IPAs are sandboxed in a separate process. They communicate with the pipeline handler through IPC.*

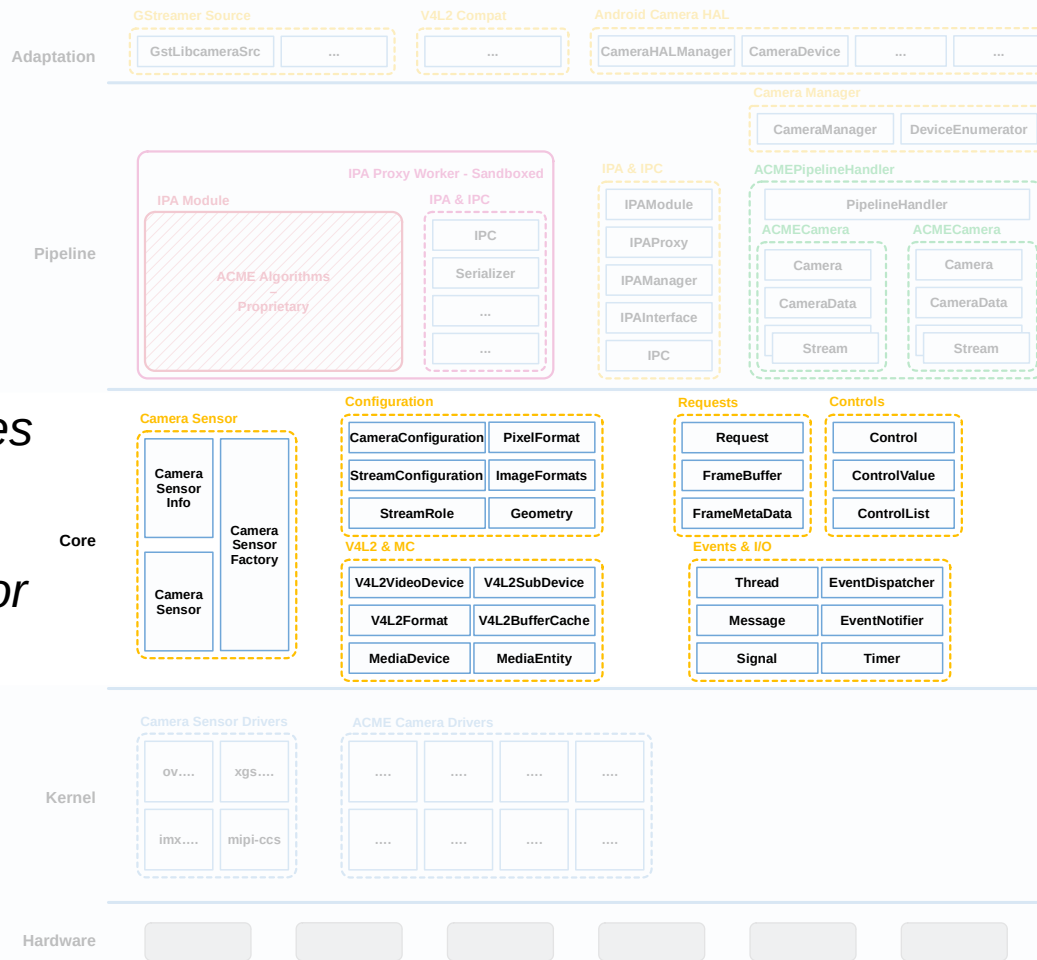


# The Image Processing Algorithms



*The IPC is handled in core components, transparently for both the pipeline handler and the IPA.*

# The Image Processing Algorithms

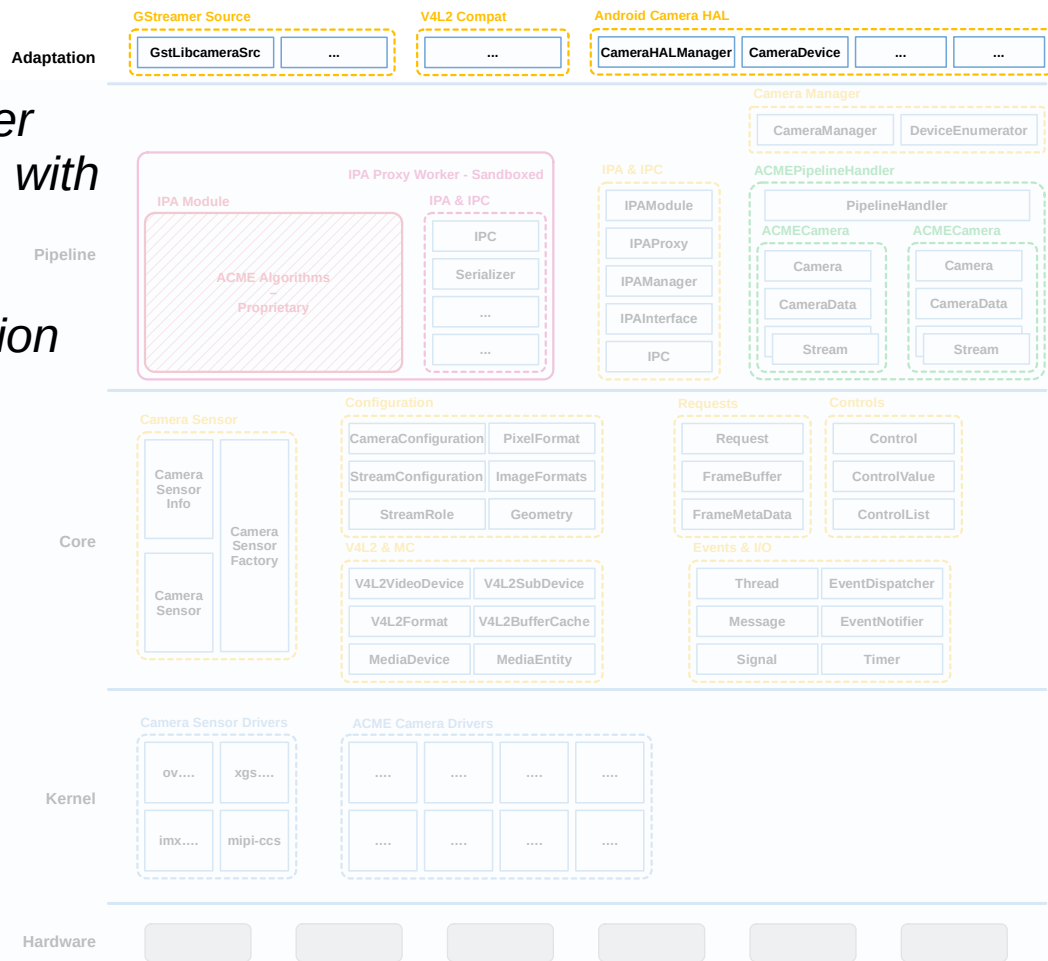


*Many helper classes ease the implementation of pipeline handlers for device vendors.*

# The Helpers and Support Classes



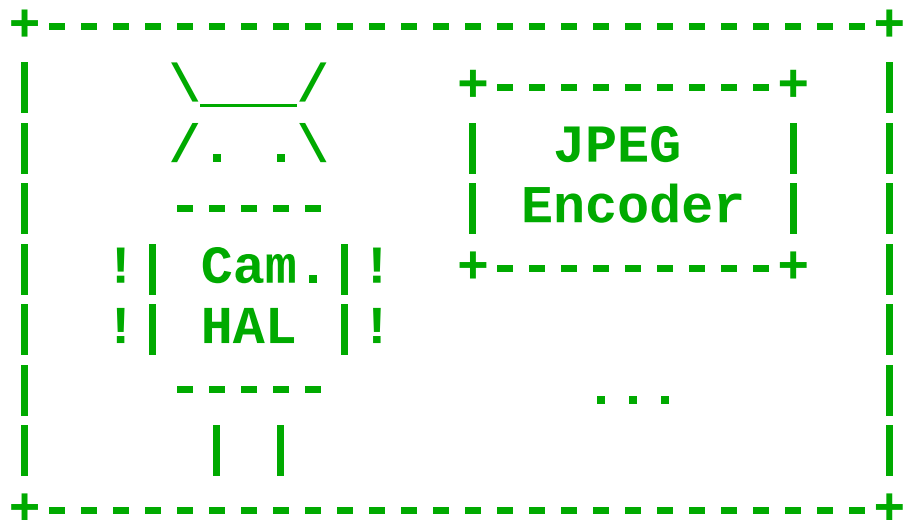
*The adaptation layer interface libcamera with other APIs and frameworks, with a single implementation for all supported devices.*



# The Adaptation Layer



+-----+  
 | Android Camera Framework |  
 +-----+



HW level

- EXTERNAL
- LEGACY
- LIMITED
- FULL
- LEVEL\_3

time  
v

*A single Android camera HAL module implementation for all devices supported by libcamera.*

+-----+  
 | libcamera |  
 +-----+



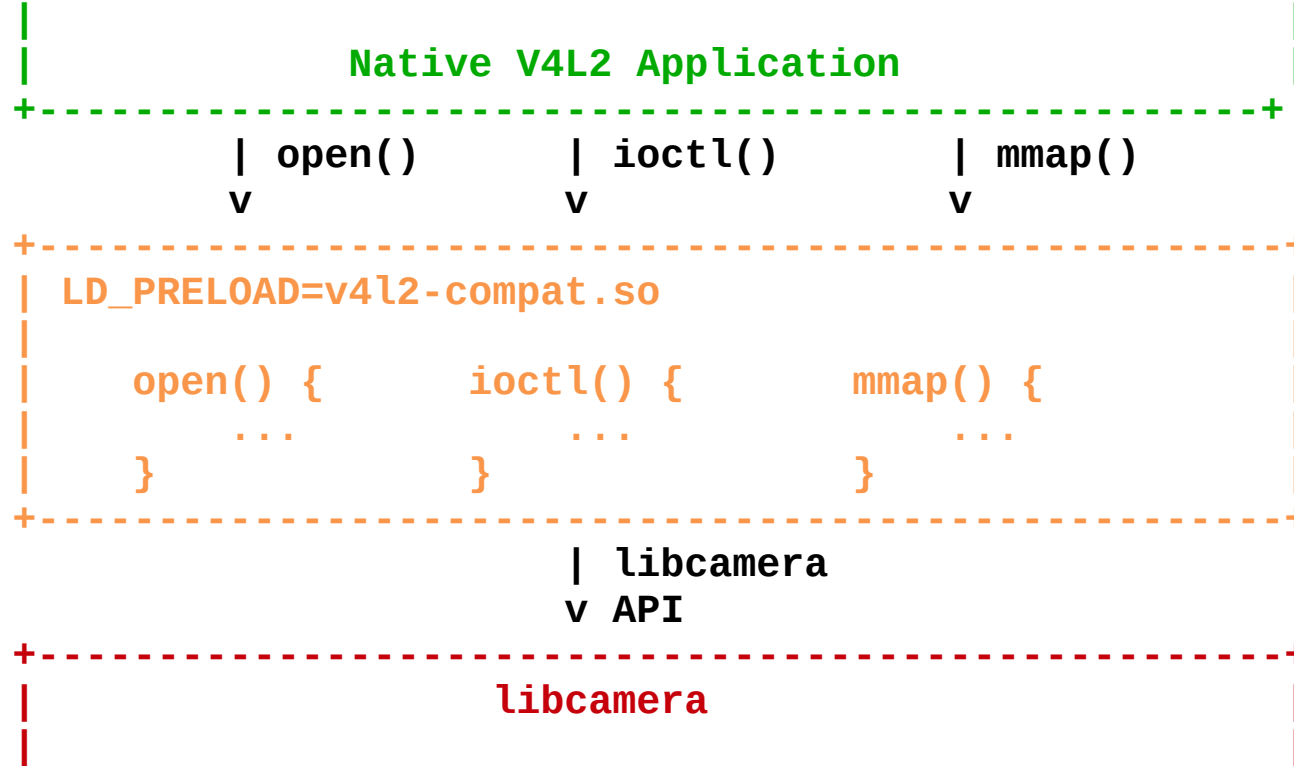
# Android Camera HAL



*“libcamerasrc” offers a  
multi-stream source  
element for GStreamer  
applications.*



**GStreamer**



*Native V4L2 applications are supported through a transparent compatibility layer.*

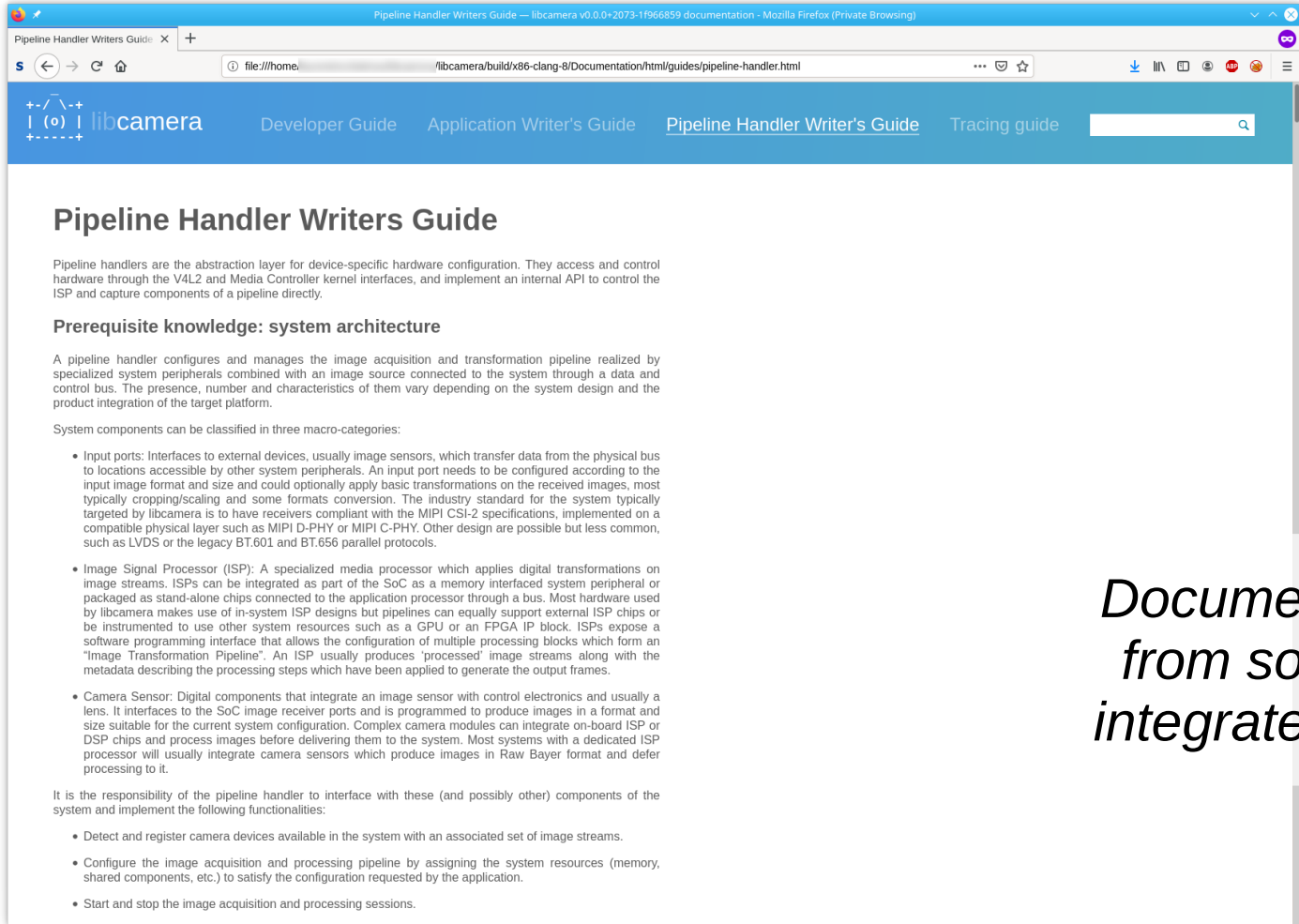
## Native V4L2 Compatibility

Features	Status
Core	Multi-camera, multi-stream, per-frame control, hotplug
Supported platforms	Raspberry Pi 3&4, Intel IPU3 (Kaby Lake), Rockchip RK3399, UVC, NXP i.MX7, Allwinner A31
IPA modules	Raspberry Pi, Intel IPU3 IPA module isolation with IPC (based on mojom IDL)
Adaptation layers	GStreamer source element (with multi-stream), Android camera HAL v3.3, V4L2 emulation
Tooling	Camera Tuning Tool (Raspberry Pi), tracing infrastructure and analysis script
Applications	cam (command line Swiss army knife), qcam (GUI), simple-cam (tutorial)
Documentation	Extensive API documentation and high-level tutorials and guides available



# Summary of Supported Features





*Documentation compiled from source tree, will be integrated in the website.*

IDEAS  
ON BOARD

# Guides

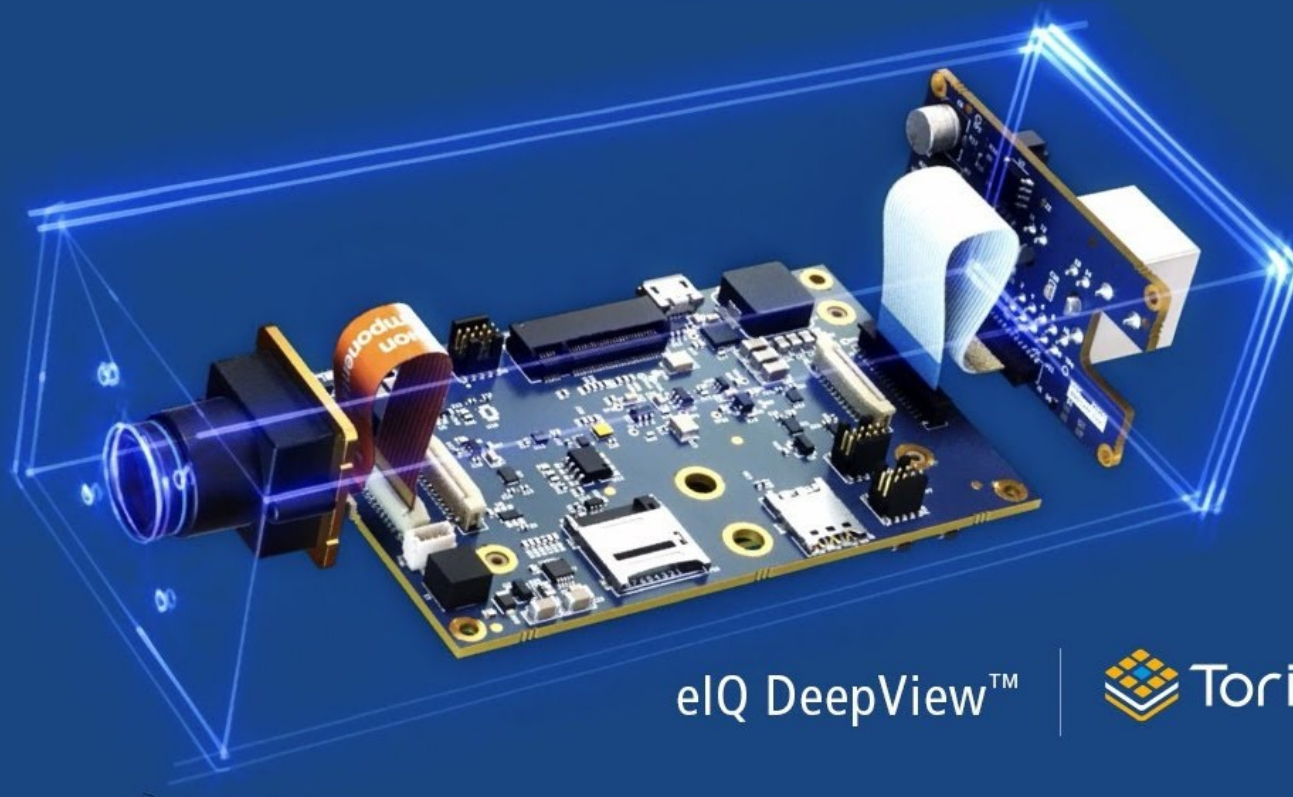


**MEDIATEK** | **OLogic**

MediaTek Pumpkin i500 (MT8385)

**New Platforms**

**IDEAS  
ON BOARD**



eIQ DeepView™

 **Torizon™**

NXP i.MX8M Plus

# New Platforms

**IDEAS**  
ON BOARD



Purism Librem 5

# New Platforms

Features	Status
New platforms	MediaTek MT8385 (with YUV sensors), NXP i.MX8M Plus, Librem 5
Open-source IPA modules	Intel IPU3, Rockchip ISP, I.MX8M Plus
Reprocessing API	Work in progress in the libcamera core, Android HAL support will follow
Controls and properties	New controls and properties are continuously added on a per-need basis
API cleanups	Moving toward the API freeze for a 1.0 release, API changes will remain backward-compatible (extensible API design, d-pointer design pattern, ...)
Language bindings	Python bindings in progress
Android LIMITED and FULL CTS compliance	Core infrastructure ready, controls and properties (static, control and dynamic metadata) being developed incrementally
Integration	Native support in Chromium web browser available at <a href="https://github.com/libcamera-org/chromium">https://github.com/libcamera-org/chromium</a> .



## Work In Progress



# Chromium (on MS Surface Go 2)



# Embedded Camera

Exploratory Group for Embedded Camera and Sensors



emva  
european machine vision association

**HOSTED BY:**

K H R  N O S<sup>®</sup>  
G R O U P

## Participation In Industry Initiatives

IDEAS  
ON BOARD

+ - / \ - +  
| (o) |  
+ - - - - +

For  
Camera  
Vendors



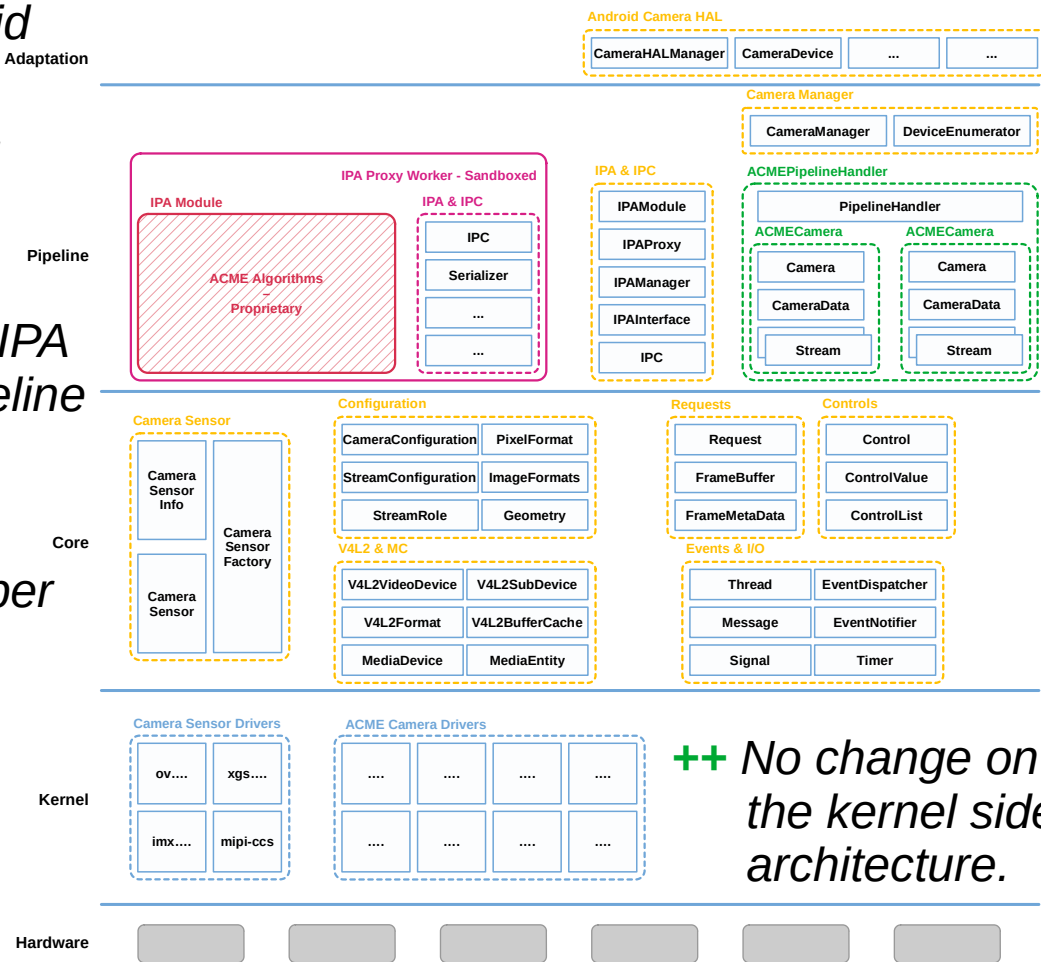


++ *Standard Android Camera HAL Implementation.*

++ *GStreamer, V4L2, ...*

!! *Custom API for IPA module <-> pipeline handler communication.*

++ *libcamera wrapper classes reduce custom code.*



!! *Pipeline handler is ACME-specific development.*

++ *Development support available.*

++ *No change on the kernel side architecture.*

!! *Implementation changes may be required to mainline drivers.*

# Platform Enablement

*We drive MC and V4L2  
standardization and  
extensions development  
according to our needs.*



---

## **Kernel APIs**

*We drive MC and V4L2  
standardization and  
extensions development  
according to our needs.*

*libcamera is a  
userspace framework,  
not a hostile takeover  
of kernel development.*



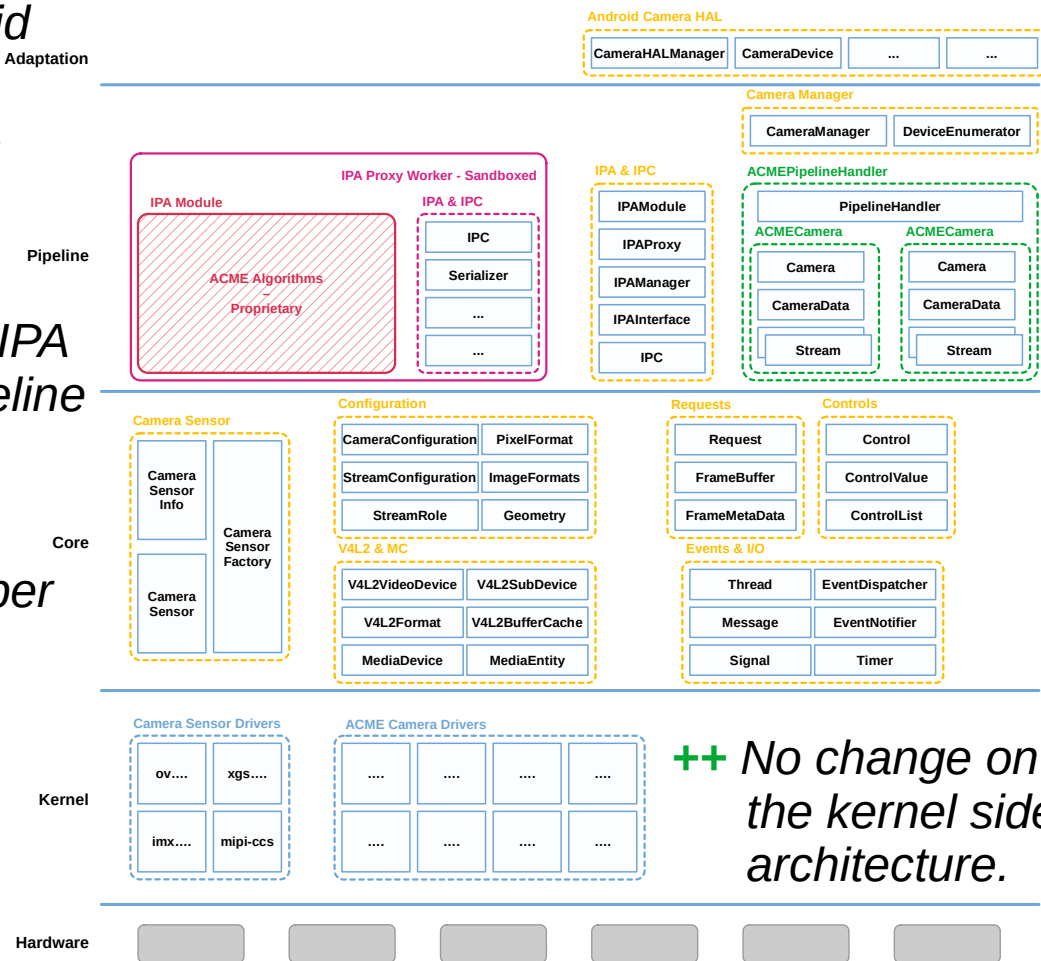
## Kernel APIs

++ *Standard Android Camera HAL Implementation.*

++ *GStreamer, V4L2, ...*

!! *Custom API for IPA module <-> pipeline handler communication.*

++ *libcamera wrapper classes reduce custom code.*



!! *Pipeline handler is ACME-specific development.*

++ *Development support available.*

++ *No change on the kernel side architecture.*

!! *Implementation changes may be required to mainline drivers.*

# Platform Enablement

*The libcamera core  
is licensed under the  
LGPL v2.1 or later.*



# Licensing

*The libcamera core  
is licensed under the  
LGPL v2.1 or later.*

*Changes need to be published  
according to the license. This  
includes pipeline handlers.*



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according to the license. This  
includes pipeline handlers.*

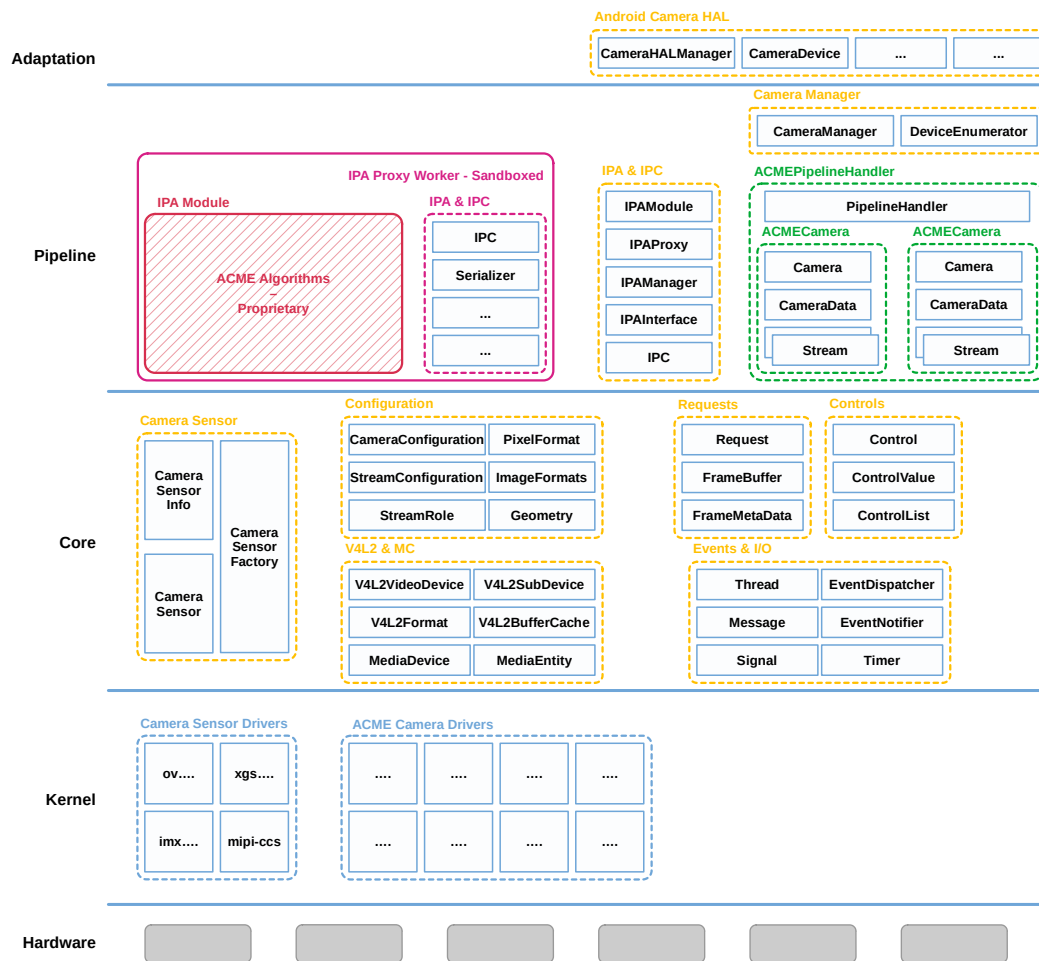
*Upstreaming is not mandatory  
but highly recommended  
(forks are costly to maintain).*



## Licensing

*Closed-source IPA modules are fully supported.*

*Pipeline handlers and IPA modules can link to third-party libraries.*



*The libcamera core, pipeline handlers and adaptation are licensed under LGPL v2.1 or later*

*Kernel code is licensed under GPL v2.0.*

# Licensing





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An  
Exciting  
Future

Features	Status
Per-stream controls	Concept approved, will be scheduled in the future.
Zero shutter lag	Will be possible through the reprocessing API. We are considering a high-level “use cases” library on top of libcamera for ZSL and similar features.
Exposure bracketing HDR	Similarly to ZSL, could be implemented in a “use cases” library. A solution for device-assisted HDR (hardware merging or software merging based on hardware-generated metadata) is needed.
Logical camera devices (W+T zoom, power saving, ...)	Not planned yet, missing development and test platform.
Still image trigger sequence (focus & flash)	Not planned yet, missing development and test platform.



## Future Features – Core

Features	Status
Open-source IPA modules	Cross-platform core library, long term work to convince device vendors
GPU-based processing	Proof of concept shader code in qcam test application, should be leveraged to create GPU-based ISP for platforms without a hardware ISP (Librem 5).
New devices support	Ongoing discussions with SoC/system vendors, community-driven effort on legacy devices (any volunteer for the N900/N9 ?)



## Future Features – Devices

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<https://sched.co/IALq>



Capturing pixels with a camera involves a number of steps, from the ADC reading the photosites in the image sensor to the final pixel values that are ready for encode/display, with various processing and transmission taking place along the way. While simple cases put most of the heavy lifting on the image sensor's side (through its embedded processor) and use a simple parallel bus for transmission, advanced cases require more work to be done outside of the sensor. In addition, modern high-speed transmission buses also bring-in more complexity. This talk will present how support for such an advanced use case was integrated into the mainline Linux kernel, using the Media and V4L2 APIs. It involves supporting a sensor using the raw Bayer RGB format, transmission over the MIPI CSI-2 bus as well as support for the Image Signal Processor (ISP) found on Allwinner platforms. A specific focus will be set on this ISP, with details about the features it implements as well as the internal and userspace APIs that are used to support it. The integration between all of the involved components will also be highlighted.

#### Speakers



#### Paul Kocialkowski

Embedded Linux Engineer, Bootlin

Paul joined Bootlin in 2018 and started with bringing support for the Allwinner VPU to mainline Linux. He went on to cover more topics related to graphics and multimedia, with various contributions to the DRM and V4L2 Linux subsystems as well as various related projects. Before that... [Read More](#) →

Wednesday September 29, 2021 3:55pm - 4:45pm PDT

[Room 4](#)

[Embedded Linux Conference \(ELC\)](#), [Streaming Media & Graphics](#)

**Experience Level** [Mid-level](#)

**Talk Type** [Virtual](#)



# New Platforms

Features	Status
HAL v3.5(+)	On the roadmap, on hold due to lack of development and test platform. Future Android camera HAL API extensions will be implemented (including extensions to the libcamera core if needed).
Zero Shutter Lag	HAL-based ZSL implemented using the libcamera reprocessing API.



## Future Features – Android HAL

Features	Status
Frameworks	PipeWire, OpenCV, Qt Multimedia, Electron, <insert your framework here>, ...
Applications	Firefox, OBS, <insert your application here>, ...
Operating Systems	Chrome OS, Android, Linux distributions, Buildroot, OpenEmbedded, ...



## Future Features – Integration

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libcamera



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<irc://chat.freenode.net/#libcamera>

[laurent.pinchart@ideasonboard.com](mailto:laurent.pinchart@ideasonboard.com)



## Contact



Thank you.

